

# PUMA 2100/2600/3100 series

High-Performance Turning Center

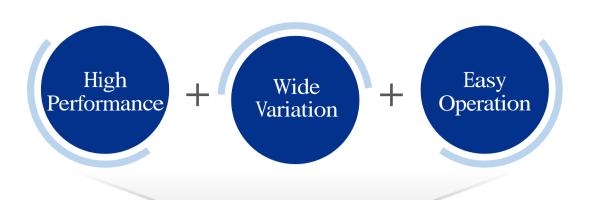


# **High-Performance Turning Center**

PUMA 2100/2600/3100 series has been developed to create full line up of high level 8" to 12" size with model variations from 2 axis to Y axis and sub spindle.

# PUMA 2100/2600/3100 series







# **High Performance**

These Doosan machines offer a high level of machining capability to provide optimum productivity for the customer.



## Rigid bed

Today's high speed / high acceleration, deceleration feed drives impose severe impact forces on the machine tool structure. This causes low frequency / large amplitude vibration which can cause deterioration in surface finish and contour definition during finish machining. Doosan's enhanced structural stability reduces the effects of vibration and provides the optimum conditions for producing unsurpassed workpiece quality.

Larger than previous

Max. 158 %

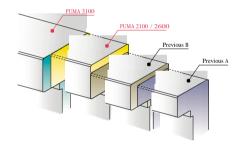
(PUMA 2100 / 2600)

Max. 154 % (PUMA 3100)



## bed guide way width

For structural stability, the guide way width and span are enlarged by 25%~50%, so that high precision in cutting is ensured.

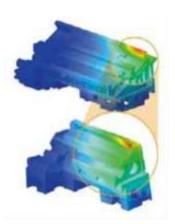


#### Stiffness

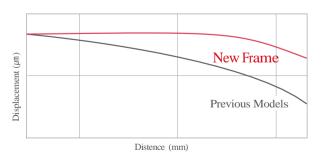
Static and Dynamic rigidity of the new PUMA

machines have been enhanced in structural

the previous model.



### Guide way deformation



Static stiffness is 3 times higher than previous



• PUMA 2100SY core machine

## Main Spindle

### Increased mounting area of headstock base to the bed

The spindle headstock has increased rigidity due to the wide surface contact between the headstock and bed way for Heavy duty cutting, Optimum surface finish, High cutting speeds, Highly accurate roundness.

larger area than previous

Max. 190 %

(in the same class)



## Sub Spindle

Mounting base area is

50 % ~ 94 %

larger than previous

Previous Model 135 / 170 mm (5.3 / 6.7 inch)

Chuck size

PUMA 2100 / 2600

175 mm (6.88 inch)



## Tooling System (On Turn-Milling)

The turret accommodates BMT55P or BMT65P tooling in which the toolholders are mounted directly to the turret's periphery with 4 large bolts. This type of mounting system BMT55P is standard on PUMA2100 turn-milling models and BMT65P is standard on PUMA2600 and PUMA3100 turn-milling models. BMT65P is available on PUMA2100 as an option.

Max. rotary tool spindle speed 5000 r/min

Max. rotary tool spindle power 5.5 kW (7.3 Hp), 15 min.

{7.5 kW (10.1 Hp), 5 min.} opt

Max. rotary tool spindle torque

47 N·m (34.6 ft-lbs) {95.5 N·m (70.4 ft-lbs)} opt



## Saddle

The broad width and long contact span of the saddle slideway ensures stability of the support structure. This coupled with the optimised spindle and bed design provides heavy duty and accurate machining capability.

Saddle guide width and span are increased in a range from

Max. 30 % to 46 % compared with previous



# Machining Capacity

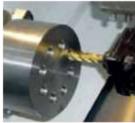
More powerful revolving motor is adapted to improve the productivity.



## End mill

Carbon steel (SM45C)

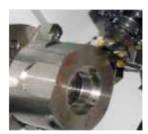
	Unit	PUMA 2100 BMT55P	PUMA 2600 BMT65P
Chip removal rate	cm³/min (inch³/min)	90 (35.43)	105 (41.34)
Tool Dia.	mm (inch) mm	18 (0.71)	20 (0.79)
Cutting Depth	(inch) mm/min	20 (0.79)	21 (0.83)
Feedrate	(ipm)	250 (9.8)	250 (9.8)



# **Tapping**

Carbon steel (SM45C)

	Unit	PUMA 2100 BMT55P	PUMA 2600 BMT65P
Rotary tool spindle speed	r/min	240	240
Tap Size		M20 x P2.5	M24 x P3
Feedrate	mm/min (ipm)	600 (23.6)	600 (23.6)



## Face mill

Carbon steel (SM45C)

	Unit	PUMA 2100 BMT55P	PUMA 2600 BMT65P
Chip removal rate	cm³/min (inch³/min)	41.9 (16.49)	53.9 (21.22)
Tool Dia.	mm (inch)	63 (2.48)	63 (2.48)
Cutting Depth	mm (inch)	3.5 (0.14)	4.5 (0.18)
Feedrate	mm/min (ipm)	190 (7.5)	190 (7.5)



# O.D turning

Carbon steel (SM45C)

	Unit	PUMA 2100	PUMA 2600
Chip removal rate	cm³/min (inch³/min)	528 (207.87)	616 (242.52)
Cutting Depth	mm (inch)	4.3 (0.17)	5.0 (0.2)
Feedrate	mm/rev (ipr)	0.55 (0.022)	0.55 (0.022)



## U-Drill dia. 63 mm (2.5 inch)

Carbon steel (SM45C)

	Unit	PUMA 2100	PUMA 2600		
Chip removal rate	cm³/min (inch³/min)	472 (185.83)	630 (248.03)		
Feedrate	mm/min (ipm)	0.15 (0.006)	0.2 (0.008)		



## Grooving

Carbon steel (SM45C)

	Unit	PUMA 2100	PUMA 2600
Chip removal rate	cm³/min (inch³/min)	169 (66.54)	241 (94.9)
Cutting Depth	mm (inch)	8 (0.31)	8 (0.31)
Feedrate	mm/rev (ipr)	0.14 (0.006)	0.2 (0.008)

<sup>•</sup> The results indicated in this catalogue are provided as example.

They may not be obtained due to differences in cutting conditions and environmental conditions during measurement.

<sup>•</sup> Turing results are obtained in the condition of standard motor.

## Accuracy

Doosan offers its customers unsurpassed levels of accuracy by applying the latest design techniques and rigorous testing processes.

### Roundness

Machine	PUMA 2600SY	
	[Belt-driven]	
Tool	TNMG16404R-W	
1001	[Nose radius 0.4mm]	
	ø60 x L50	
Workpiece	(ø2.4 x L2.0 inch)	
	Carbon steel [SM45C]	
Spindle Speed	3500 r/min	
Cutting Depth	0.025 mm (0.001 inch)	
Feedrate	0.025 mm/rev (0.001 ipr)	



Users enjoy stable performance in all types of operations from heavy-duty cutting to high speed machining.

Work material	Aluminum (AL2024)
Cutting speed	250 (9842.5) m/min (ipm)
Feedrate	0.08 (0.003) mm/rev (ipr)
Cutting depth	0.2 (0.008) mm (inch)
Tool	Diamond [nose R0.8]

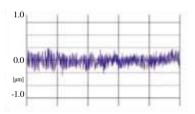
PUMA 2600SY	0.5	
PUMA 2000S1	0.5	
Current PUMA		3.2

## Roughness

Ra 0.11µm (Ra 0.004 µinch)

Rz 0.83µm (Rz 0.033 µinch)

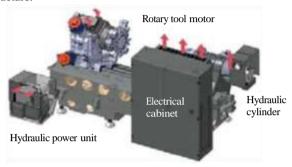
Rmax 0.92µm (Rmax 0.036 µinch)



Material	Carbon steel (SM45C)	
Work Size	ø60 x L50 mm (ø2.4 x L2.0 inch)	
Spindle speed	3500 r/min	
Feed	0.025 mm/rev (0.001 ipr)	
Depth	0.025 mm (0.001 inch)	
Holder	PTGNR2020 M16	
Insert	TNMG160404 R-W (R0.4)	

## Heat elimination layout

One very important design concept is to reduce the effects of heat sources in the machine. Heat shields and fan motors are used to prevent the transmission of heat to the machine structure.



## Coolant chiller on

Thermal displacement and dimensional accuracy are greatly influenced by oil temperature in a machine. Coolant Temperature Control unit prevents the coolant from heating. Especially, when using oil-based coolant, the oil temperature can become extremely high.



\*Please contact Doosan in these cases

### Inertia estimates function for C-axis and



This function can estimate the C-axis inertia which is affected by variation in workpiece weight. It is possible to optimise the Velocity Gain and Acc/Dec Time Constant and therefore improve the C-axis accuracy.

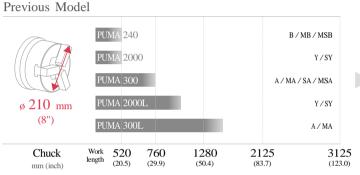




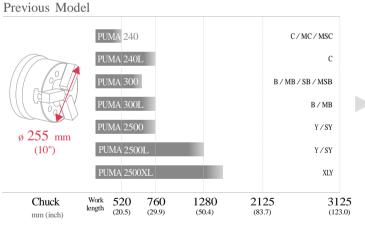
# **Wide Variation**

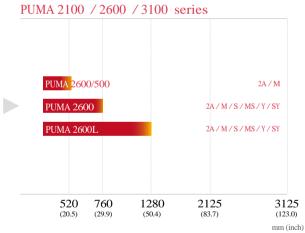
A wide variety of machine specifications from 2-axis models to turning centers with sub spindles is available to meet your production requirements.

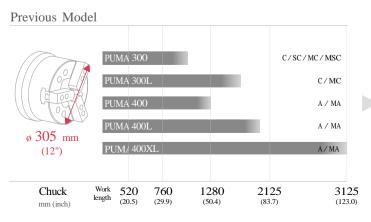
#### PUMA 2100/2600/3100 series

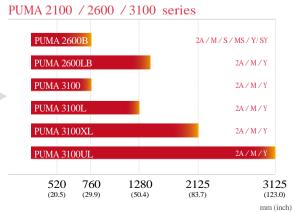


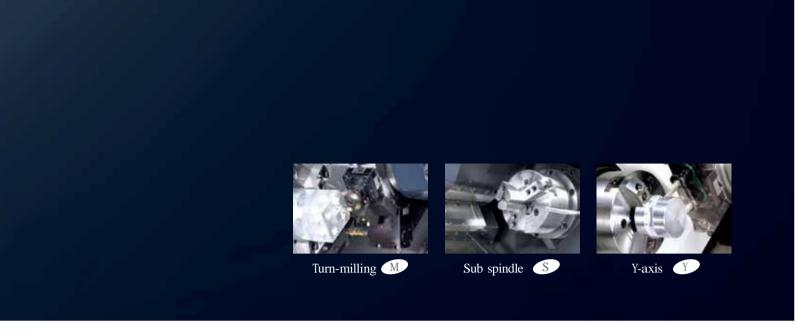














## PUMA 2100

Turning		_ Turn-milling	7
std. L S	LS	M LM	MS LMS
		Y	SY LSY
Max. work length		mm (inch)	520 / 760 [L] (20.5 / 29.9 [L])
Chuck [Main / Sub]		mm (inch)	210 / 175 (8 / 6)
Max. turning dia.		mm (inch)	480, 406 <sup>1)</sup> {376 <sup>2)</sup> } (18.9,16.0 <sup>1)</sup> {14.8 <sup>2)</sup> })
	X-axis	mm (inch)	<b>260</b> (10.2)
Travel	Z-axis	mm (inch)	590 / 830 [L] (23.2 / 32.7 [L])
	Y-axis	mm (inch)	105 <±52.5> (4.1<±2.1>)

{ } : Option



## PUMA 2600\*

Turning		Turn-milling	g
std. L S	LS	M LM	MS MS M50 MB LMB MSB LMSB
/500 b LB Sb LSB		Y LY	SY LSY YB LYB SYB LSYB
Max. work length		mm (inch)	520 (500 machine) / 760 / 1280 [L] (20.5 / 29.9 / 50.4 [L])
Chuck [Main / Sub]		mm (inch)	255 / 175 (10 / 6)
Max. turning dia. mm (inch) 480, 376 <sup>2)</sup> (18.9,		480, 376 <sup>2)</sup> (18.9, 14.8 <sup>2)</sup> )	
X-axis		mm (inch)	<b>260</b> (10.2)
Travel	Z-axis	mm (inch)	590 (500 machine) / 830 / 1350 [L] (23.2 / 32.7 / 53.1 [L])
	Y-axis	mm (inch)	105 <±52.5> (4.1<±2.1>)
C. Outil			

<sup>\* :</sup> PUMA 2600B Chuck size: 305 mm (12.0 inch)

 $\{\ \}$ : Option



- 1) : PUMA 2100M [LM] / MS [LMS] / Y [LY] / SY [LSY] 2) : PUMA 2100, 2600M [LM] / MS [LMS] / Y [LY] / SY [LSY] 3) : PUMA 3100M/LM/XLM/ULM/Y/LY/XLY/ULY

## **PUMA 3100**

std. L	XL	UL	M LM XLM ULM					
			Y LY XLY ULY					
			760 / 1280 [L] (29.9 / 50.4 [L])					
Max. work l	Max. work length		2125 [XL] / 3125 [UL]					
			(83.7 [XL] / 123.0 [UL])					
Chuck [Main	n]	mm (inch)	<b>305</b> (12)					
Max. turning	g dia.	mm (inch)	525, 420 <sup>3)</sup> (20.7, 16.5 <sup>3)</sup> )					
	X-axis	mm (inch)	<b>293</b> (10.2)					
T1	7:-	(* 1)	830 / 1350 [L] / 2190 [XL] / 3190 [UL]					
Travel	Z-axis	mm (inch)	(32.7 / 53.1 [L] / 86.2 [XL] / 125.6 [UL])					
Y-axis		mm (inch)	130 <±65> (5.1 <±2.6>)					

{ } : Option

# Machining range

We have added a high-rigidity bed and special functions and equipment for machining long workpieces. It is the definitive bar workmachine, eliminating all compromise.



Model	A (Max. turning length)	B (Max. turning diameter)	C (Door open space)	
PUMA 2100 / S	520 (20.5)	480 (18.9)	(05 (07 4)	
PUMA 2100M / MS / Y / SY	520 (20.5)	406 (16.0)	695 (27.4)	
PUMA 2100L / LS	7(0(20.0)	480 (18.9)	015 (22 1)	
PUMA 2100LM / LMS / LY / LSY	760 (29.9)	406 (16.0)	815 (32.1)	
PUMA 2600 / S	760 (29.9)	480 (18.9)	815 (32.1)	
PUMA 2600M / MS / Y / SY	700 (29.9)	376 (14.8)	813 (32.1)	
PUMA 2600L / LS	1290 (50.4)	480 (18.9)	1275 (54.1)	
PUMA 2600LM / LMS / LY / LSY	1280 (50.4)	376 (14.8)	1375 (54.1)	
PUMA 2600/500	520 (20.5)	480 (18.9)	695 (27.4)	
PUMA 2600M/500	320 (20.3)	376 (14.8)		
PUMA 2600B/LB	725 / 1245	480 (18.9)	915 (22.1)	
PUMA 2600MB/LMB	(28.5 / 49.0)	376 (14.8)	815 (32.1)	
PUMA 2600SB/MSB	725 (28.5)	480 / 376 (18.9 / 14.8)	915 (22.1)	
PUMA 2600YB/SYB	123 (26.3)	376 (14.8)	815 (32.1)	
PUMA 3100	7(0(20.0)	525 (20.7)	050 (22.5)	
PUMA 3100M / Y	760 (29.9)	420 (16.5)	850 (33.5)	
PUMA 3100L	1290 (50.4)	525 (20.7)	1440 (567)	
PUMA 3100LM / LY	1280 (50.4)	420 (16.5)	1440 (56.7)	
PUMA 3100XL	2125 (92.7)	525 (20.7)	2260 (80.0)	
PUMA 3100XLM / XLY	2125 (83.7)	420 (16.5)	2260 (89.0)	
PUMA 3100UL	2125 (122.0)	525 (20.7)	2260 (129.2)	
PUMA 3100ULM / ULY	3125 (123.0)	420 (16.5)	3260 (128.3)	

Unit: mm (inch)

## Main spindle

To achieve a high level of stability during machining, improvements in rigidity have been the main focus in the design process. The mounting areas of main and Sub-spindles have been significantly widened and the spindle length shortened to minimise vibration. Spindle bearing diameter has been increased to improve rigidity. This also allows a larger through bore size for the sub-spindle. Spindles are available as belt type or built-in motor type.

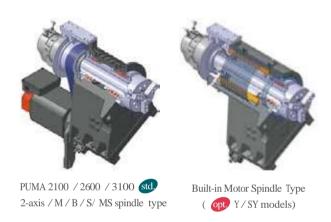
### bar work capacity

PUMA 3100

PUMA 2100	Ø65 mm (Ø2.6 inch)
PUMA 2600	Ø76 mm (Ø3.0 inch)
PUMA 2600B PUMA 3100	Ø102 mm (Ø4.0 inch)

## Power & torque of spindle

Model	Speed (r/min)	Power [kW (Hp)]	Max. Torque [N·m (ft-lbs)]
PUMA 2100	4500	std. 18.5 (24.8)	183 (135.1)
	5000 [Built-in]	opt. 22 (29.5)	358 (264.2)
PUMA 2600	3500	std. 22 (29.5)	240 (177.1)
	4000 [Built-in]	opt. 22 (29.5)	599 (442.1)
PUMA 2600B	2800	std. 22 (29.5)	1123 (828.8)
PUMA 3100	2800	std. 22 (29.5)	1123 (828.8)
	3000 [Built-in]	opt. 30 (40.2)	1203 (887.8)



## 

To make rotary tooling more effective, precise circular positioning of the spindle is necessary. The sub-spindle has 0.001° full C-axis contour function which is same with the function of main spindle. Moreover, power and torque are increased for more cutting capability.

### Power & torque of spindle

Model	Speed (r/min)	Power [kW (Hp)]	Max. Torque [N⋅m (ft-lbs)]
PUMA 2100	4500	std. 7.5 (10.1)	85 (61.3)
PUMA 2600	6000 [Built-in]	opt. 15 (20.1)	134 (98.9)

### Enhanced sub-spindle

Model	Previous Model	PUMA 2100 / 2600			
Chuck size	135 / 170  mm  (5 / 6  inch)	175 mm (6 inch)			
Spindle bearing diameter	75/90  mm (3.0/3.5  inch)	90 mm (3.5 inch)			
Bar capacity	43 / 53 mm (1.7 / 2.1 inch)	48 mm (1.9 inch)			

## Tailstock configuration (A) (M) (Y)

3 types of tail stocks such as manual, programmable and servo driven can be offered to customers as alternative choices.

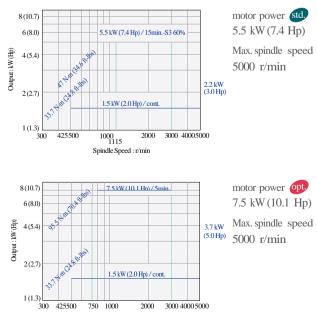
	Model		PUMA 2100 / L series	PUMA 2600 / L series PUMA 3100 / L series	PUMA 3100XL / UL series		
		Live center MT4	std.	Not avaliable			
		Built-in center MT3	opt.	Not available			
Manual type	7	Live center MT5	N-41: -1-1-	std.			
	A CONTRACTOR OF THE PARTY OF TH	Built-in center MT4	Not avaliable	opt.	N. d. P. LL		
		Live center MT4		NT . P 11	Not avaliable		
	13	Built-in center MT3	opt.	Not avaliable			
Programmable type		Live center MT5			_		
турс	The state of the s	Built-in center MT4	Not avaliable	opt.			
		Built-in center MT5			std.		
		Live center MT4		Not avaliable			
Servo d		Built-in center MT3	opt.				
	Version	Live center MT5	N. 11.11		Not avaliable		
-		Built-in center MT4	Not avaliable	opt.			

## Turret Turn (A) (S) Turn-milling (M) (MS) (T) (SY)

The turret has been designed based on a modular concept. It provides improved tool clearance and optimum rigidity. The milling turret version includes 24 position indexing to increase the available tool capacity.

		Turning PUMA 2100 / 2600 / 3100	Turn-Milling PUMA 2100 / 2600 / 3100			
No. of tool stations						
		12/12/10 st	12 st {24*st opt, 16**st opt.}			
Tooling sy	stem	Doosan Base	BMT55P / 65P / 65P			
	OD	25 x 25 mm (	1.0 x 1.0 inch)			
Tool size	ID	ø50 mm (ø2.0 inch)	ø40/50/50 mm (ø1.5/2.0/2.0 inch)			
Curvic coupling		ø230 mm (9.1 inch)				
Turret index time		0.15 s				

## Rotary tool power torque diagram



## 



In the Y-axis plane, tools can move in a plus or minus direction perpendicular to the Z-axis and spindle center line. Viewed from the operator's perspective, this Y-axis motion is toward or away from the door of the machine while X-axis moves from floor to ceiling. Y-axis enables various shape of cutting. Y-axis is realized virtually by the linear interpolation and synchronous movement of X1 and X2-axis that make it possible to lower machine height for stability.

#### Y-axis travel

PUMA 2100 / 2600 105 mm

[±52.5mm] (4.1 inch [±2.1 inch])

PUMA 3100 130 mm

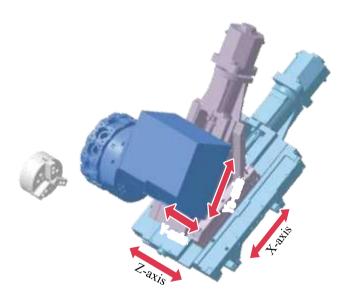
[±65.0mm] (5.1 inch [±2.6 inch])

Y-axis rapid 10 m/min (7.4 ipm)



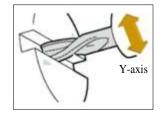
#### Configuration of Y-axis

Model	PUMA 2100/2600	PUMA 3100
Bed slant angle	30°	30°
X slant angle	30°	30°
X-Y slant angle	30°	30°
Y-axis travel	±52.5 mm (±2.1 inch)	±65.0 mm (±2.6 inch)

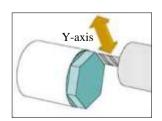


### All enough in single setup

Simultaneous XYZ motion provides the capability milling complex shapes. In addition, the rigidly clamped C-axis disc brake enables heavy duty and precision machining.



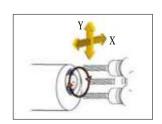
On-center face groove



Poly-side machine



Off-center side groove



Y&X-axis circular interpolation

YY

ХХ

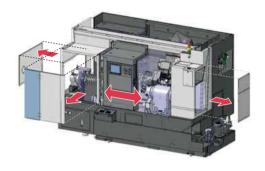
# **Improved Maintainability**

Maintainability is one of the crucial criteria that Doosan placed at the forefront of machine development. Large openings in the machine paneling facilitate access to the underlying maintenance units like lubricant oil tank and pneumatic fittings.

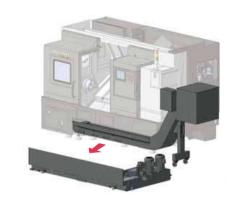
PUMA 2100/2600/3100 series

## Easy to Access for Maintenance

By new machine cover design concept, maintenance locations are easily seen, and wider openings allow easier access.

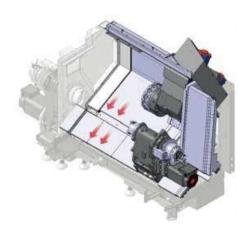


The coolant tank can be pulled out at the front and does not require the chip conveyor to be removed.



## Fully Wrapped Machine

To minimize the thermal effect on the machine, heat of chips should be prevented from being transmitted to bed and guide ways. Guide ways are fully covered so that heat can be isolated. Also, telescopic covers have strengthened linkage system that ensures durability. (only PUMA 2100/2600)





## **Power Saving Function**

### Automatic machine light turns off

This is smart function that can turn off the machine light automatically when no user touches key board of operation panel during specified time.





### Automatic machine sleep

If CNC operator's panel has not been used for a time, the motors for spindle, servo axis, coolant pump and chip conveyor etc. are powered off automatically. It is effective to reduce standby power. Save up stand by power from 10 to 14%.



## **EZ Function**

This function is to support simple setting of Tool Setter and improve the function to set tail stock position automatically with recorded tail stock position.

#### EZ automatic tail stock function

This function enables the position setting of tail stock automatically. In programmable tail stock, the Z-axis position of tail stock is recorded automatically



as the clamped position of tail stock. When tail stock needs to move to the other position, Z-axis moves to the pre-recorded position of Z-axis and tail stock unclamps by the button operation of OP pane.

#### EZ tool setter function

This is specially designed for improving the efficiency of CNC turning center. If a user selects target tool to be checked by Tool Setter in manual mode, its moving axis is advanced forward to make the setter easy to touch off the tools, and the axis moves backward after touching the tool automatically.



## Easy Operation Package

These DOOSAN software packages have been customized to provide user-friendly functions.

## Programming



#### G Code list

Operator can check the meaning of each G-code.



#### M Code list

Operator can check the meaning of each M-code.



#### Calculator

Operator can calcute numerical formula in relation to arc and hole easily.



#### Servo tailstock thrust setting

Thrust force control is simple to set up using the specially designed servo-driven tail stock thrust setting software.

- Input value directly
- Select one of the initially set values

## Operation / Maintenance



#### Tool load monitor opt

The main function of this software is to detect overload when a tool is wrong, and change it to an other tool. Stop machine to protect a tool holder and next tools by detecting overload caused by tool breakage or its wear. Use editable tool life management for spare tools. Monitor load meter for all spindles and axes. If the tool load reaches abnormal band recorded in "Set data", the software issues an feed hold alarm or skips the tool.



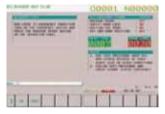
#### Operation rate - user log in

A major determinant of efficiency is the cost associated with setting up the equipment to make a particular product. This software can be used to manage machine operation rate of 3 operators. Total machine operation and real machining time for a month can be recorded and measured. It helps to evaluate and monitor each operational efficiency. To keep it secure, Password setting is essential.



#### Back up custom data

This can be used to record tool load information detected in "Tool load monitor" for all tools used during cutting. By reloading recorded data in tool table, Tool Load Monitor software can compare the actual tool load with a recorded load pattern.



#### Turret recovery help

The software is to help users recover turret step by step from trouble situation where it does not work. It can quickly recover your valuable machine.

## Easy Guide i

Operation Guidance, which supports entire operations on an all-in-one screen for daily machining including creating a program on the machine.

- Uses one display screen to perform all operations including programming, checking by animation, and real machining.
- User-Friendly Operation : Soft key selection of comprehensive cycle library
- Easy programming
   Based on ISO-code program format, complex machining motions can be created easily by this menu format.
- Machine status window
   Machine status such as actual position,
   feedrate and load meter are always displayed.
- Realistic machining simulation
   3-D solid model machining simulation is available.
- Intuitive menu selecting
   Menu can be selected easily and intuitively by soft-keys with icons.



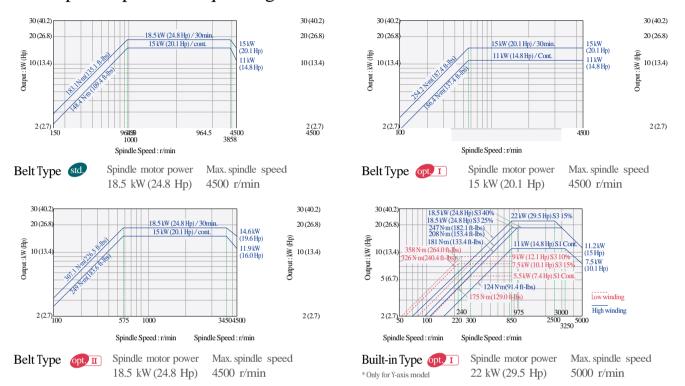
Cycle machining menus for both of lathe machining and milling are available



Programming time can be reduced

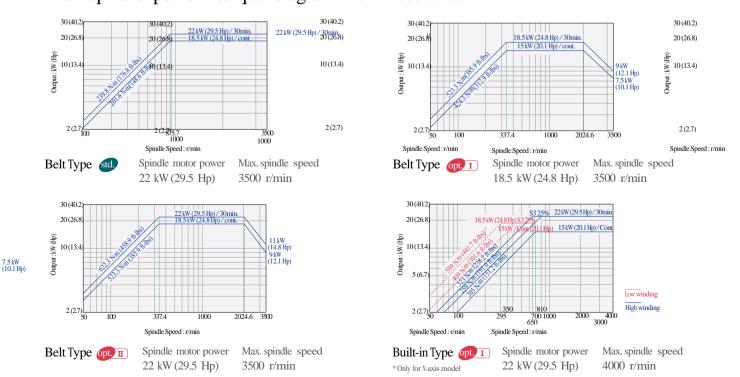
# Spindle Power - Torque Diagram

## Main spindle power - torque diagram PUMA 2100 series



## Main spindle power - torque diagram PUMA 2600 series

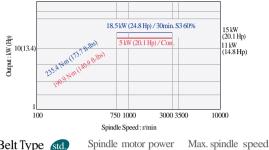
eed:r/min



Spindle

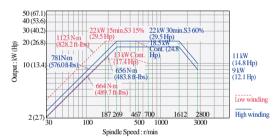
# Spindle Power - Torque Diagram

## Main spindle power - torque diagram PUMA 2600 / 500, PUMA 2600M / 500

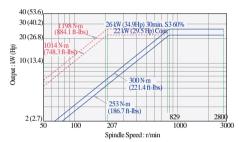


Belt Type std. 18.5 kW (Hp) 3500 r/min

## Main spindle power - torque diagram PUMA 2600B / 3100 series



Spindle motor power Max. spindle speed Belt Type std. 22 kW (29.5 Hp) 2800 r/min

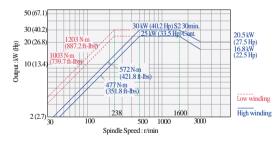


Belt Type with Spindle motor power 26 kW (34.9 Hp) Gear Box opt

Max. spindle speed 2800 r/min

\*\* PUMA 2600B/LB, PUMA 3100/L/XL/UL only

## Main spindle power - torque diagram PUMA 3100 series

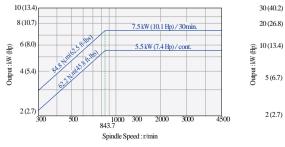


Built-in Type opt I

Spindle motor power 30 kW (40.2 Hp)

Max. spindle speed 3000 r/min

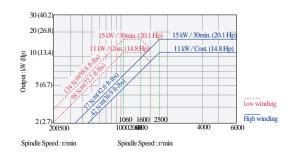
## Sub spindle power - torque diagram PUMA 2100 / 2600



Belt Type std.

Spindle motor power 7.5 kW (10.1 Hp)

Max. spindle speed 4500 r/min



Built-in Type opt

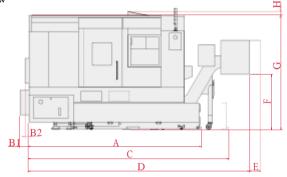


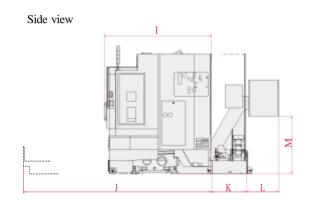
Spindle motor power 15 kW (20.1 Hp)

Max. spindle speed 6000 r/min

PUMA 2100 Unit: mm (inch)





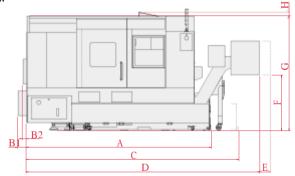


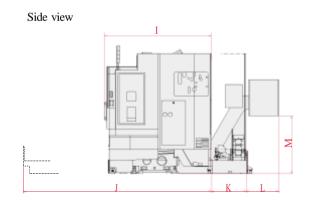
Model	A	B1	B2	С	D	Е	F	G	Н	I	J	K	L	М
PUMA 2100/S/M/MS	3150 (124.0)	160 (6.3)	-	3650 (143.7)	4030 (158.7)	200 (7.9)	1010 (39.8)	1903 (74.9)	-	1863 (73.3)	3240 (127.6)	523 (20.6)	646 (25.4)	1007 (39.6)
PUMA 2100Y/SY	3150 (124.0)	160 (6.3)	25 (1.0)	3650 (143.7)	4030 (158.7)	200 (7.9)	1010 (39.8)	2090 (82.3)	73 (2.9)	1863 (73.3)	3240 (127.6)	523 (20.6)	646 (25.4)	1007 (39.6)
PUMA 2100L/LS/LM/LMS	3370 (132.7)	160 (6.3)	-	3870 (152.4)	4250 (167.3)	200 (7.9)	1010 (39.8)	1903 (74.9)	-	1863 (73.3)	3240 (127.6)	523 (20.6)	646 (25.4)	1007 (39.6)
PUMA 2100LY/LSY	3370 (132.7)	160 (6.3)	25 (1.0)	3870 (152.4)	4250 (167.3)	200 (7.9)	1010 (39.8)	2090 (82.3)	73 (2.9)	1863 (73.3)	3240 (127.6)	523 (20.6)	646 (25.4)	1007 (39.6)

 $B1:Belt\,type.$  Standard Spindle Motor, Optional Spindle Motor is different.  $B2:Built\text{-}In\,type.$ 

PUMA 2600 Unit: mm (inch)







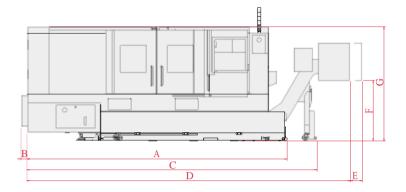
Model	A	B1	B2	С	D	Е	F	G	Н	I	J	K	L	M
PUMA 2600/500 PUMA 2600M/500	3150 (124.0)	220 (8.7)	-	3650 (143.7)	4030 (158.7)	200 (7.9)	1010 (39.8)	1903 (74.9)	-	1863 (73.3)	3240 (127.6)	523 (20.6)	646 (25.4)	1007 (39.6)
PUMA 2600/S/M/MS	3370 (132.7)	230 (9.1)	-	3870 (152.4)	4250 (167.3)	200 (7.9)	1010 (39.8)	1903 (74.9)	-	1863 (73.3)	3240 (127.6)	523 (20.6)	646 (25.4)	1007 (39.6)
PUMA 2600B/SB/MB/MSB	3370 (132.7)	333 (13.1)	-	3870 (152.4)	4250 (167.3)	200 (7.9)	1010 (39.8)	1903 (74.9)	-	1863 (73.3)	3240 (127.6)	523 (20.6)	646 (25.4)	1007 (39.6)
PUMA 2600Y/SY	3370 (132.7)	230 (9.1)	135 (5.3)	3870 (152.4)	4250 (167.3)	200 (7.9)	1010 (39.8)	2090 (82.3)	73 (2.9)	1863 (73.3)	3240 (127.6)	523 (20.6)	646 (25.4)	1007 (39.6)
PUMA 2600YB/SYB	3370 (132.7)	333 (13.1)	-	3870 (152.4)	4250 (167.3)	200 (7.9)	1010 (39.8)	2090 (82.3)	73 (2.9)	1863 (73.3)	3240 (127.6)	523 (20.6)	646 (25.4)	1007 (39.6)

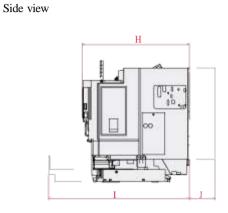
B1 : Belt type. Standard Spindle Motor, Optional Spindle Motor is different. B2 : Built-In type.

PUMA 2600L

Unit: mm (inch)







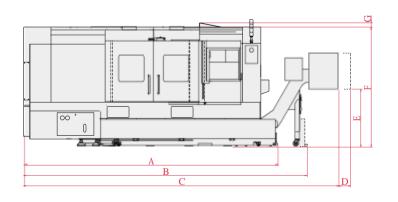
Model	A	В	С	D	Е	F	G	Н	I	J
PUMA 2600L/LS/LM/LMS	4335 (170.7)	-	4835 (190.4)	5389 (212.2)	200 (7.9)	1010 (39.8)	1903 (74.9)	1965 (77.4)	3240 (127.6)	523 (20.6)
PUMA 2600LB/LSB/LMSB	4335 (170.7)	103 (4.1)	4835 (190.4)	5389 (212.2)	200 (7.9)	1010 (39.8)	1903 (74.9)	1965 (77.4)	3240 (127.6)	523 (20.6)

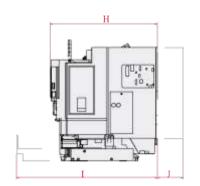
PUMA 2600LY

Unit: mm (inch)

Side view

Front view

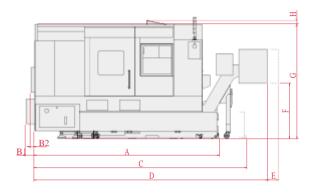




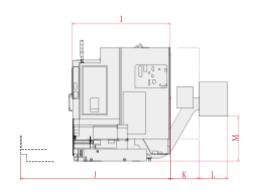
Model	A	В	С	D	Е	F	G	Н	I	J
PUMA 2600LY/LSY/LYB/LSYB	4435	4935	5489	200	1010	2090	73	1965	3240	523
	(174.6)	(194.3)	(216.1)	(7.9)	(39.8)	(82.3)	(2.9)	(77.4)	(127.6)	(20.6)

PUMA 3100 Unit: mm (inch)

Front view



#### Side view

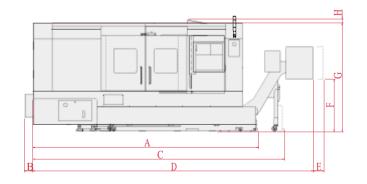


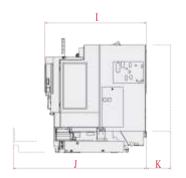
Model	A	B1	B2	С	D	Е	F	G	Н	I	J	K	L	M
PUMA 3100/M	3575	332	250	4095	4486	200	1010	1997	20	2003	3410	523	646	1007
	(140.7)	(13.1)	(9.8)	(161.2)	(176.6)	(7.9)	(39.8)	(78.6)	(0.8)	(78.9)	(134.3)	(20.6)	(25.4)	(39.6)
PUMA 3100Y	3575	332	250	4095	4486	200	1010	2214	105	2003	3410	523	646	1007
	(140.7)	(13.1)	(9.8)	(161.2)	(176.6)	(7.9)	(39.8)	(87.2)	(4.1)	(78.9)	(134.3)	(20.6)	(25.4)	(39.6)

B1 : Belt type. Standard Spindle Motor, Optional Spindle Motor is different. B2 : Built-In type.

**PUMA 3100L** Unit:mm (inch)

Front view Side view

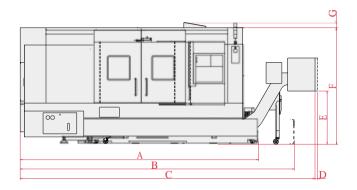


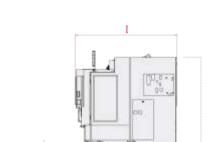


Model	A	В	С	D	Е	F	G	Н	I	J	K
PUMA 3100L/LM	4455	72	5135	5527	50	1010	1997	20	2105	3410	523
	(175.4)	(2.8)	(202.2)	(217.6)	(2.0)	(39.8)	(78.6)	(0.8)	(82.9)	(134.3)	(20.6)

PUMA 3100LY

Front view





Side view

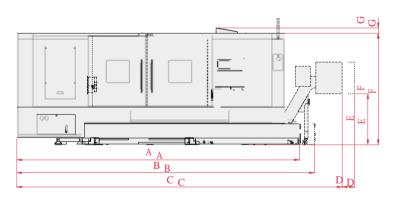
Side view

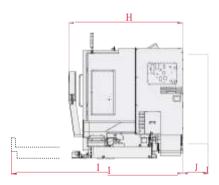
Model	A	В	С	D	Е	F	G	I	J	K
PUMA 3100LY	4530	5210	5602	50	1010	2214	105	2105	3410	523
	(178.4)	(205.2)	(220.6)	(2.0)	(39.8)	(87.2)	(4.1)	(82.9)	(134.3)	(20.6)

# PUMA 3100XL / UL

Unit:mm (inch)

Front view





Model	A	В	С	D	Е	F	G	Н	I	J
PUMA 3100XL/XLM	5615 (221.1)	6015 (236.8)	6443 (253.7)	245 (9.6)	1010 (39.8)	2208 (86.9)	-	2280 (89.8)	3400 (133.9)	523 (20.6)
PUMA 3100XLY	5615 (221.1)	6015 (236.8)	6443 (253.7)	245 (9.6)	1010 (39.8)	2208 (86.9)	107 (4.2)	2280 (89.8)	3400 (133.9)	523 (20.6)
PUMA 3100UL/ULM	6585 (259.3)	7265 (286.0)	7670 (302.0)	268 (10.6)	1010 (39.8)	2208 (86.9)	-	2280 (89.8)	3400 (133.9)	523 (20.6)
PUMA 3100ULY	6585 (259.3)	7265 (286.0)	7670 (302.0)	268 (10.6)	1010 (39.8)	2208 (86.9)	107 (4.2)	2280 (89.8)	3400 (133.9)	523 (20.6)

# Standard & Optional Features

: standard features	:option	∴: Pre-discussion is required	X : Not available
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Oution		PU	MA 2100(I	L)/2600(1	L)		PUMA	3100 Std.	/L	PUMA 3100 XL/UL		
Option	2-axis Std.	M	S	MS	Y	SY	2-axis Std.	M	Y	2-axis Std.	M	Y
Special chucks	Δ	$\triangle$	$\triangle$	$\triangle$	$\triangle$	$\triangle$	Δ	$\triangle$	$\triangle$	Δ	$\triangle$	$\triangle$
Soft jaws												
Dual pressure chucking	0	$\circ$	0	0	0	0	0	$\circ$	0	0	$\circ$	
Hydraulic chuck pressure switch	0	$\circ$	0	0	0	0	0	$\circ$	0	0	$\circ$	0
Chuck clamp confirmation	0	0	0	0	0	0	0	0	0	0	0	0
Tail stock center: Live center			X	X		Х				Х	Х	X
Tail stock center: Dead center	0	$\circ$	X	X	0	Х	0	$\circ$	0			
Tail stock : Manual			Х	X		Х				Х	Х	Х
Tail stock : Programmable	0	0	Х	X	0	Х	0	0	0			
Tail stock : Servo driven	0	0	X	Х	0	Х	0	0	0	Х	Х	Х
Automatic quill advance & retract	0	0	Х	Х	0	Х	0	0	0	0	0	0
Rotary tool holder	Х	•	Х			•	Х		•	Х	•	
Tool setter : Manual	0	0	0	0	0	0	0	0	0	0	0	0
Tool setter : Automatic_electric	0	0	0	0	0	0	0	0	0	0	0	0
Auto workpiece measurement	0	0	0	0	0	0	0	0	0	0	0	0
Linear scale (X-axis)	0	0	0	0	0	0	0	0	0	0	0	0
Linear scale (Z-axis)	0	0	0	0	0	0	0	0	0	0	0	0
Linear scale (Y-axis)	Х	Х	Х	Х	0	0	Х	Х	0	Х	Х	0
Feedback system : Absolute position encoder	•	•				•	•		•	•	•	
Bar feeder interface	0	0	0	0	0	0	0	0	0	0	0	0
Bar puller	$\triangle$	$\triangle$	$\triangle$	$\triangle$	$\triangle$	$\triangle$	Δ	$\triangle$	$\triangle$	Х	Х	Х
Workpiece ejector	Х	Х	0	0	Х	0	Х	Х	Х	Х	Х	Х
Parts catcher with box	0	0	0	0	0	0	Δ	$\triangle$	$\triangle$	Х	Х	Х
Parts catcher with conveyor	0	0	0	0	0	0	Δ	Δ	$\triangle$	Х	Х	Х
Workpiece cut off confirmation	Х	Х	0	0	Х	0	Х	Х	Х	Х	Х	Х
Automatic front door : with safety device	0	0	0	0	0	0	0	0	0	0	0	0
Chip conveyor type: Right side	0	0	0	0	0	0	0	0	0	0	0	0
Chip conveyor type: Rear side *1	0	0	0	0	0	0	0	0	0	Х	Х	Х
Chip bucket	0	0	0	0	0	0	0	0	0	0	0	0
TSC for main / left spindle	0	0	0	0	0	0	0	0	0	0	0	0
Oil skimmer	0	0	0	0	0	0	0	0	0	0	0	0
Coolant level switch	0	0	0	0	0	0	0	0	0	0	0	0
Coolant chiller	0	0	0	0	0	0	0	0	0	0	0	0
Oil mist collector	0	0	0	0	0	0	0	0	0	0	0	0
Coolant blower	0	0	0	0	0	0	0	0	0	0	0	0
Air blower	0	0	0	0	0	0	0	0	0	0	0	0
Air gun	0	0	0	0	0	0	0	0	0	0	0	0
Signal tower (yellow, red, green)	0	0	0	0	0	0	0	0	0	0	0	0
Gantry loader	Δ	Δ	$\triangle$	$\triangle$	$\triangle$	$\triangle$	Δ	Δ	$\triangle$	Δ	Δ	Δ
V-stand for shaft workpiece	0	0	Х	Х	0	Х	0	0	0	Х	Х	Х

<sup>\*1 :</sup> PUMA 2100/L, PUMA 2600, PUMA 3100 only

# PUMA 3100XL / UL

O: option X: Not available

				٥.	option		vanabic
Steady	, Doct	PUMA	2100	PUMA	2600	PUMA	3100
Sicauy	/ Kest	Std.	L	Std.	L	Std./L	XL/UL
	Hydraulic	0	0	0	0	0	0
Type	Programmable	0	0	0	0	0	0
	Servo driven°1	Х	Х	Х	Х	Х	0
	SLU-1	0	0	0	0	Х	Х
	SLU-2	0	0	0	0	0	0
	SLU-B3.1	Х	0	0	0	Х	Х
Size	SLU-3.1	Х	Х	Х	Х	0	0
	SLU-3.2	Х	Х	Х	Х	Х	0
	SLU-4	Х	Х	Х	Х	Х	O*2
	SLU-B4	Х	Х	Х	Х	Х	0

# High pressure coolant

Model		PUMA 2100 /	2600/3100
Model		60Hz	50Hz
Standard	1.5 bar	0.4 kW x 0.15 MPa x 40 L/min (0.5 Hp x 21.8 psi x 10.6 galon/min)	0.4 kW x 0.15 MPa x 40 L/min (0.5 Hp x 21.8 psi x 10.6 galon/min)
	5 bar	0.9 kW x 0.45 MPa x 30 L/min (1.2 Hp x 65.3 psi x 7.9 galon/min)	0.9 kW x 0.30 MPa x 30 L/min (1.2 Hp x 43.5 psi x 7.9 galon/min)
ontion	7 bar	1.5 kW x 0.7 MPa x 30 L/min (2.0 Hp x 101.5 psi x 7.9 galon/min)	1.5 kW x 0.5 MPa x 30 L/min (2.0 Hp x 72.5 psi x 7.9 galon/min)
option	10 bar*	2.2 kW x 1.0 MPa x 30 L/min (3.0 Hp x 145.0 psi x 7.9 galon/min)	2.2 kW x 0.7 MPa x 30 L/min (3.0 Hp x 101.5 psi x 7.9 galon/min)
	15 bar*	3.7 kW x 1.45 MPa x 30 L/min (5.0 Hp x 210.3 psi x 7.9 galon/min)	4.0 kW x 2.8 MPa x 20 L/min (5.0 Hp x 145.0 psi x 7.9 galon/min)
Special	28 bar*	4.0 kW x 2.8 MPa x 20 L/min (5.4 Hp x 406.6 psi x 5.3 galon/min)	4.0 kW x 1.95 MPa x 20 L/min (5.0 Hp x 282.8 psi x 5.3 galon/min)
option	70 bar*	5.5 kW x 7.0 MPa x 30 L/min (7.4 Hp x 1015.0 psi x 7.9 galon/min)	5.5 kW x 7.0 MPa x 26 L/min (7.4 Hp x 1015.0 psi x 6.9 galon/min)

<sup>\*</sup> Recommend using coolant chiller

# Machine Specifications PUMA 2100 series

	Description	Unit	PUMA 2100/L	PUMA 2100M/LM	PUMA 2100MS/LMS	PUMA 2100S/LS				
	Swing over bed	mm (inch)		780	(30.7)					
	Swing over front door	mm (inch)		680	(26.8)					
	Swing over saddle	mm (inch)		630	(24.8)					
Capacity	Recom. Turning diameter	mm (inch)		210	(8.3)					
	Max. turning diameter	mm (inch)	480 (18.9)	406 (	16.0)	480 (18.9)				
	Max. turning length	mm (inch)		520 / 760 (	20.5 / 29.9)					
	Bar working diameter	mm (inch)		65 (	(2.6)					
	Travel distance X-axis	mm (inch)	260 [20+240] (10.2 [0.8+9.4])		7+203] 2.2+8.0])	260 [20+240] (10.2 [0.8+9.4])				
`ravels	Z-axis	mm (inch)	590 / 830 (23.2 / 32.7)							
	Y-axis	mm (inch)		·						
	B-axis	mm (inch)	- 590 / 830 (23.2 / 32.							
	Rapid traverse X-axis	m/min (ipm)	30 (1181.1)							
	Z-axis	m/min (ipm)	30 (1181.1)							
eedrates	Y-axis	m/min (ipm)		-						
	B-axis	m/min (ipm)	- 30 (1181.1)							
	Spindle speed (Belt Type)	r/min	4500							
	Spindle speed (Built-in Type)	r/min	-							
<b>I</b> ain	Spindle nose			ASA .	A2#6					
pindle	Spindle bearing diameter (Front)	mm (inch)			(4.7)					
	Spindle through hole diameter	mm (inch)			(3.0)					
	Min. spindle indexing angle (C-axis)	deg	_		0.001					
	No. of tool stations st		12	12.	[24]	12				
	OD tool size	mm (inch)	25 (1.0)		1.0 [0.8])	25 (1.0)				
urret	Boring bar diameter	mm (inch)	50 (2.0)		1.6 [1.3])	50 (2.0)				
urret	Indexing time (1st swivel time)	s	30 (2.0)		15	30 (2.0)				
	Rotary tool spindle speed	r/min			000 -					
	Quill diameter	mm (inch)		(3.1)						
ail stock	Quill bore taper (Live)	mm (men)		(3.1) T#4	-					
an stock	Compressed air supply	mm (inch)		(3.1)	-					
	Spindle speed (Belt [Built-in])	r/min	001	(3.1)	1500	NF 1				
		1/111111		-	4500 ASA A					
	Spindle nose	mm (inch)		-						
ub-spindle	Spindle bearing diameter (Front)	` ′		-	90 (					
	Spindle through hole diameter	mm (inch)		-	62 (					
	Min. spindle indexing angle (C-axis)	deg		- 10 5 /15 /	0.0	01				
	Main spindle motor	kW (Hp)		18.5 / 15 (2	24.8 / 20.1)	0.1.77.4)				
Iotors	Sub spindle motor	kW (Hp)		-	7.5 / 5.5 (1	0.1 / 7.4)				
	Rotary tool spindle motor	kW (Hp)		-	5.5 (7.4)	-				
	Coolant pump motor	kW (Hp)		0.4	(0.5)					
ower ource	Electric power supply (Rated capacity	) kVA	35.63	38.41	45.63	42.85				
	Machine height	mm (inch)		1900	(74.8)					
	Machine dimension length	mm (inch)		3310/3530 (130.3/139.0)						
Machine size	width	mm (inch)	(inch) 1863 (73.3)							
	Machine weight	kg (lb)	4850 / 5350 (10692 3 / 11794 6)	5000 / 5500 (11023.0 / 12125.2)	5450 / 5950 (12015.0 / 13117.3)	5300 / 5800 (11684.3 / 12786.6)				

<sup>•</sup> The specifications and information above-mentioned may be changed without prior notice.
• For more details, please contact Doosan

# Machine Specifications PUMA 2100 /2600 series

	Description		Unit	PUMA 2100Y/LY	P 2100SY/LSY	PUMA 2600/L	PUMA 2600M/LM	
	Swing over bed		mm (inch)		780	(30.7)		
	Swing over front door		mm (inch)		680	(26.8)		
	Swing over saddle		mm (inch)		630 (	24.8)		
Capacity	Recom. Turning diameter		mm (inch)	210	(8.3)	255	(10.0)	
	Max. turning diameter		mm (inch)	406	(16.0)	480 (18.9)	376 (14.8)	
	Max. turning length		mm (inch)	520 / 760 (	20.5 / 29.9)	760 / 1280	(29.9 / 50.4)	
	Bar working diameter		mm (inch)	65 (	(2.6)	76	(3.0)	
	Travel distance	X-axis	mm (inch)	-	7+203] 2.2+8.0])	260 [20+240] (10.2 [0.8+9.4])	260 [72+188] (10.2 [2.8+7.4])	
ravels	_	Z-axis	mm (inch)	590 / 830 (	23.2 / 32.7)	830 / 1350	(32.7 / 53.1)	
2.015		Y-axis	mm (inch)	105 [±52.5] (4	4.13 [±2.065])		-	
		B-axis	mm (inch)	-	590 / 830 (23.2 / 32.7)		-	
	Rapid traverse	X-axis	m/min (ipm)		30 (1	181.1)		
		Z-axis	m/min (ipm) 30 (118			181.1)		
eedrates	_	Y-axis	m/min (ipm)	10 (3	393.7)		-	
	_	B-axis	m/min (ipm)	-	30 (1181.1)		-	
	Spindle speed (Belt Type)		r/min	45		35	500	
	Spindle speed(Built-in Type)		r/min		00	3500		
	Spindle nose				A2#6	- ASA A2#8		
lain pindle	Spindle bearing diameter (Front)		mm (inch)		(4.7)	140 (5.5)		
	Spindle through hole diameter		mm (inch)		(3.0)		(3.4)	
	Min. spindle indexing angle (C-axis)		deg		001	-	0.001	
	No. of tool stations	(C-axis)	st		4] [16]	12	12 [24]	
	OD tool size		mm (inch)					
urret	Boring bar diameter		mm (inch)		1.0 [0.8] [1.0])	25 (1.0) 50 (2.0)	25 [20] (1.0 [0.8])	
unet				40 [32] [32] (	1.6 [1.3] [1.6])		50 [40] (2.0 [1.6])	
	Indexing time (1st swivel tim	ie)	s r/min	F.O.	00	.15		
	Rotary tool spindle speed		mm (inch)			- 5000		
. 1 1 .	Quill diameter		IIIII (IIICII)	80 (3.1)	-		0(3.9)	
il stock	Quill bore taper (Live)		(l.)	MT#4	-		T#5	
	Quill travel	1)	mm (inch)	80 (3.1)	4500 550007	100	0 (3.9)	
	Spindle speed (Belt [Built-in]	D	r/min	-	4500 [6000]		-	
	Spindle nose			-	ASA A2-5		-	
ub-spindle	Spindle bearing diameter (F		mm (inch)	-	90 (3.5)		-	
	Spindle through hole diame		mm (inch)	-	62 (2.4)		-	
	Min. spindle indexing angle	(C-axis)	deg	-	0.001		-	
	Main spindle motor		kW (Hp)	18.5 / 15 (2	24.8 / 20.1)	22 / 18.5 (	(29.5 / 24.8)	
Iotors	Sub spindle motor		kW (Hp)	-	7.5 / 5.5 (10.1 / 7.4)		-	
	Rotary tool spindle motor kW		kW (Hp)	5.5	(7.4)		-	
	Coolant pump motor		kW (Hp)		0.4	(0.5)		
ower ource	Electric power supply (Rated capacity) kVA		41.32	48.54	40.72	43.5		
	Machine height		mm (inch)	2163	(85.2)	1900	(74.8)	
	Machine dimension	length	mm (inch)	3310/3530(	130.3 / 139.0)	3600 / 4335 (	(141.7 / 170.7)	
Machine size	_	width	mm (inch)		(73.3)	1863 / 1965	5 (73.3 / 77.4)	
	Machine weight		kg (lb)	5450 / 5950 (12015.0 / 13117.3)	5900 / 6400 (13007.1 / 14109.4)	5400 / 6700 (11904.8 / 14770.8)	5550 / 6850 (12235.5 / 15101.4)	

<sup>•</sup> The specifications and information above-mentioned may be changed without prior notice.

<sup>•</sup> For more details, please contact Doosan

# Machine Specifications PUMA 2600 series

	Description	Unit	PUMA 2600MS/LMS	PUMA 2600S/LS	PUMA 2600Y/LY	PUMA 2600SY/LSY	
	Swing over bed	mm (inch)		780	(30.7)		
	Swing over front door	mm (inch)		680	(26.8)		
	Swing over saddle	mm (inch)		630	(24.8)		
Capacity	Recom. Turning diameter	mm (inch)		255 (	10.0)		
	Max. turning diameter	mm (inch)	376 (14.8)	480 (18.9)	376	(14.8)	
	Max. turning length	mm (inch)		760 / 1280	(29.9 / 50.4)		
	Bar working diameter	mm (inch)		76 (	3.0)		
	Travel distance	-axis mm (inch)	260 [72+188] (10.2 [2.8+7.4])	260 [20+240] (10.2 [0.8+9.4])	260 [72+188]	(10.2 [2.8+7.4])	
Travels	2	Z-axis mm (inch)		830 / 1350 (	32.7 / 53.1)		
na vers	1	-axis mm (inch)	-		105 [±52.5] (4	4.13 [±2.065])	
	I	3-axis mm (inch)	830/1350 (	(32.7/53.1)	-	830/1350 (32.7/53.1)	
	Rapid traverse X	-axis m/min (ipm)		30 (1:	181.1)		
	_	Z-axis m/min (ipm)		30 (1:			
Feedrates	_	/-axis m/min (ipm)				393.7)	
	_	3-axis m/min (ipm)	30 (11	181.1)	-	30 (1181.1)	
	Spindle speed (Belt Type)	r/min	50(1	35			
	Spindle speed (Built-in)				40	00	
Main	Spindle nose			ASA A			
Main Spindle	Spindle bearing diameter (Fr	ont) mm (inch)		140			
•	Spindle through hole diameter			86(			
	Min. spindle indexing angle (		0.001	-		001	
	No. of tool stations	st st	12 [24]	12		4] [16]	
	OD tool size	mm (inch)	25 [20] (1.0 [0.8])	25 (1.0)		1.0 [0.8] [1.0])	
Turret	Boring bar diameter	mm (inch)	50 [40] (2.0 [1.6])	50 (2.0)			
Turret	Indexing time (1st swivel time		30 [40] (2.0 [1.0])	0.		1.6 [1.3] [1.6])	
		e) s r/min	5000	0.	5000		
	Rotary tool spindle speed		3000	-			
m 1 . 1	Quill diameter	mm (inch)	<u> </u>	•	100 (3.9)	-	
Tail stock	Quill bore taper (Live)	and Carlo	-	•	MT#5	-	
	Quill travel	mm (inch)	-		100 (3.9)	4500 5 50007	
	Spindle speed (Belt [Built-in])	r/min	4500		-	4500 [6000]	
	Spindle nose			A2-5	-	ASA A2-5	
Sub-spindle	Spindle bearing diameter (Fr			3.5)	-	90 (3.5)	
	Spindle through hole diameter			2.4)	-	62 (2.4)	
	Min. spindle indexing angle (		0.0		-	0.001	
	Main spindle motor	kW (Hp)		22 / 18.5 (2	29.5 / 24.8)		
Motors	Sub spindle motor	kW (Hp)	7.5 / 5.5 (		-	7.5 / 5.5 (10.1 / 7.4)	
	Rotary tool spindle motor	kW (Hp)	5.5 [7.5] (7.4 [10.1])	-		7.4 [10.1])	
	Coolant pump motor	kW (Hp)		0.4 (	(0.5)		
Power source	Electric power supply (Rated of	capacity) kVA	51.65	48.86	46.4	54.55	
	Machine height	mm (inch)	1900	(74.8)	2163	(85.2)	
	Machine dimension 1	ength mm (inch)	3600 / 4335 (	141.7 / 170.7)	3600 / 4435 (	141.7 / 174.6)	
Machine size		width mm (inch)		1863 / 1965	(73.3 / 77.4)		
	Machine weight	kg (lb)	6000 / 7300 (13227.5 / 16093.5)	5850 / 7150 (12896.9 / 15762.8)	6000 / 7300 (13227.5 / 16093.5)	6450 / 7750 (14219.6 / 17085.6)	

<sup>•</sup> The specifications and information above-mentioned may be changed without prior notice.
• For more details, please contact Doosan

# Machine Specifications PUMA 2600 series

	Description		Unit	PUMA 2600/500	PUMA 2600M/500	PUMA 2600B/LB	PUMA 2600MB/LMB	
	Swing over bed		mm (inch)	780 (30.7)				
	Swing over front door		mm (inch)	680 (26.8)				
	Swing over saddle		mm (inch)	630 (24.8)				
apacity	Recom. Turning diameter		mm (inch)	255	(10.0)	305	(12.0)	
	Max. turning diameter		mm (inch)	480 (18.9)	376 (14.8)	480 (18.9)	376 (14.8)	
	Max. turning length		mm (inch)	520	(20.5)	725 [1245]	(28.5 [49.0])	
	Bar working diameter		mm (inch)	65 (2.6)		102	2 (4.0)	
	Travel distance	X-axis	mm (inch)	260 [20+240] (10.2 [0.8+9.4])	260 [72+188] (10.2 [2.8+7.4])	260 [20+240] (10.2 [0.8+9.4])	260 [72+188] (10.2 [2.8+7.4])	
avels		Z-axis	mm (inch)	590	(23.2)	830[1350]	(32.7[53.1])	
		Y-axis	mm (inch)	m (inch)				
	B-axis		mm (inch)		-			
	Rapid traverse X-axis		m/min (ipm)	30 (1181.1)				
		Z-axis	m/min (ipm)			181.1)		
eedrates		Y-axis	m/min (ipm)		-			
		B-axis	m/min (ipm)		-			
	Spindle speed (Belt Type)		r/min	3500 (	(137.8)	2800	(110.2)	
	Spindle nose			ASA A2-8		A2-11		
ain oindle	Spindle bearing diameter	(Front)	mm (inch)	140 (5.5)		160 (6.3)		
mule	Spindle through hole dian	neter	mm (inch)	86 (3.4) 115 (4.5)		5 (4.5)		
	Min. spindle indexing angl	le (C-axis)	deg		0.0	01		
	No. of tool stations		st	12	12 [24]	12	12 [24]	
	OD tool size		mm (inch)	25 (1.0)	25 [20] (1.0 [0.8])	25 (1.0)	25 [20] (1.0 [0.8])	
rret	Boring bar diameter		mm (inch)	50 (2.0)	50 [40] (2.0 [1.6])	50 (2.0)	50 [40] (2.0 [1.6])	
	Indexing time (1st swivel t	ime)	s		0.	15		
	Rotary tool spindle speed		r/min	-	5000	-	5000	
	Quill diameter		mm (inch)		100	(3.9)		
il stock	Quill bore taper (Live)			MT#5				
	Quill travel		mm (inch)		100	(3.9)		
	Spindle speed (Belt [Built-	-in])	r/min		-			
	Spindle nose				-			
ub-spindle	Spindle bearing diameter (Front)		mm (inch)		-			
	Spindle through hole diameter		mm (inch)		-			
	Min. spindle indexing angl	le (C-axis)	deg		-			
	Main spindle motor		kW (Hp)	18.5/15 (24.8/20.1) 22/18.5 (29.5/24.8)		(29.5/24.8)		
	Sub spindle motor		kW (Hp)	-				
Iotors	Rotary tool spindle motor		kW (Hp)	-	5.5 (7.4)	-	5.5 (7.4)	
	Coolant pump motor		kW (Hp)	0.4 (0.5)				
ower ource	Electric power supply (Rate	ed capacity)	kVA	40.72	44.42	40.72	44.42	
	Machine height		mm (inch)		1900	(74.8)		
	Machine dimension	length	mm (inch)	3370 (	(132.7)	3700 [4438]	(145.7 [174.7])	
Machine size		width	mm (inch)		1863	(73.3)		
	Machine weight		kg (lb)	4900 (10802.5)	5000 (11023.0)	5500 [6800] (12125.2 [14991.2])	5650 [6950] (12455.9 [15321.9])	

 $<sup>\</sup>bullet$  The specifications and information above-mentioned may be changed without prior notice.

<sup>•</sup> For more details, please contact Doosan

# Machine Specifications PUMA 2600 series

	Description		Unit	PUMA 2600SB	PUMA 2600MSB	PUMA 2600YB	PUMA 2600SYB		
	Swing over bed		mm (inch)		780	(30.7)	1		
	Swing over front door		mm (inch)	680 (26.8)					
	Swing over saddle		mm (inch)	630 (24.8)					
Capacity	Recom. Turning diameter		mm (inch)	305 (12.0)					
	Max. turning diameter		mm (inch)	480 (18.9)	480 (18.9) 376 (14.8)				
	Max. turning length		mm (inch)		725 (	28.5)			
	Bar working diameter		mm (inch)		102	(4.0)			
	Travel Travel distance X-axis		mm (inch)	260 (10.2)	20+240 (0.8+9.4)	260	(10.2)		
		Z-axis	mm (inch)		830 (	32.7)			
Travels		Y-axis mm (inch)			- 105 (4.1)				
		B-axis	mm (inch)	830 (32.7)		-	830 (32.7)		
	Rapid traverse X-axis m/min (ipm) 30 (1181.1)		81.1)						
	Z-axis m/min (ipm) 30 (1181.1)								
Feedrates		Y-axis	m/min (ipm)	- 10 (393.		393.7)			
		B-axis	m/min (ipm)	30 (1181.1)		-	30 (1181.1)		
	Spindle speed (Belt Type	)	r/min			I			
	Spindle nose			ASA A2-11					
Main	Spindle bearing diameter	(Front)	mm (inch)	160 (6.3)					
Spindle	Spindle through hole dia	meter	mm (inch)	115 (4.5)					
	Min. spindle indexing ang	gle (C-axis)	deg	- 0.001					
	No. of tool stations		st	12	12 12 [24]				
	OD tool size		mm (inch)	25 (1.0) 25 [20] (1.0 [0.8])					
Turret	Boring bar diameter		mm (inch)	50 (2.0) 50 [40] (2.0 [1.6])					
	Indexing time (1st swivel	time)	S	0.15					
	Rotary tool spindle speed		r/min	-		5000			
	Quill diameter		mm (inch)	100 (3.9)					
Tail stock	Quill bore taper (Live)				MT	#5			
	Quill travel		mm (inch)	100 (3.9)					
	Spindle speed (Belt [Buil	t-in])	r/min	4500 (177.2)		-	4500 (177.2)		
	Spindle nose			ASA A2#5		-	ASA A2#5		
Sub-spindle	Spindle bearing diameter	(Front)	mm (inch)	90 (	(3.5)	-	90 (3.5)		
	Spindle through hole dia	meter	mm (inch)	62 (2.4)		-	62 (2.4)		
	Min. spindle indexing ang	gle (C-axis)	deg			-	0.001		
	Main spindle motor		kW (Hp)		22/18.5 (2	29.5/24.8)			
	Sub spindle motor		kW (Hp)	7.5/5.5 (10.1/7.4) - 7.5/5.5 (10.1/7.4)		7.5/5.5 (10.1/7.4)			
Motors	Rotary tool spindle motor		kW (Hp)	- 5.5 (7.4)					
	Coolant pump motor		kW (Hp)		0.4 (	0.5)			
Power source	Electric power supply (Ra	ted capacity)	kVA	48	.86	46.40	54.55		
	Machine height		mm (inch)	1900	(74.8)	2163	(85.2)		
	Machine dimension	length	mm (inch)		3700 (	145.7)			
Machine size		width	mm (inch)		1863	(73.3)			
	Machine weight		kg (lb)	5950 (13117.3)	6100 (13448.0)	6100 (13448.0)	6550 (14440.1)		

<sup>[]:</sup>Option

<sup>•</sup> The specifications and information above-mentioned may be changed without prior notice.

<sup>•</sup> For more details, please contact Doosan

# Machine Specifications PUMA 3100 series

	Description	Unit	PUMA 3100/L/XL/UL	PUMA 3100M/LM/XLM/ULM	PUMA 3100Y/LY/XLY/ULY		
	Swing over bed			850 (33.5)			
	Swing over front door		720 (28.3)* / 850 (33.5)**				
	Swing over saddle	mm (inch)	670 (26.4)				
Capacity	Recom. Turning diameter	mm (inch)	305 (12.0)				
	Max. turning diameter	mm (inch)	525 (20.7)	420 (1	16.5)		
	Max. turning length	mm (inch)	760 /	1280 / 2125 / 3125 (29.9 / 50.4 / 83.7 / 12	23.0)		
	Bar working diameter	mm (inch)		102 (4.0)			
	Travel distance X-axis	mm (inch)	293 [30.5+262.5] (11.5 [1.2+10.3])	293 [83+210] (1:	1.5 [3.3+8.3])		
	Z-axis	mm (inch)	830/1350/2190/3190(32.7/53.1/86.2/125.6)		5.6)		
ravels	Y-axis	mm (inch)			130 [±65] (5.1 [±2.6])		
	B-axis	mm (inch)		-			
	Rapid traverse X-axis	m/min (ipm)		30 (1181.1)			
	Z-axis	m/min (ipm)	30/30/30/26(1181.1/1181.1/1023.6)		3.6)		
Feedrates	Y-axis	m/min (ipm)			10 (393.7)		
	B-axis	m/min (ipm)		-			
	Spindle speed (Belt Type)	r/min		2800			
	Spindle speed(Built-in Type)	r/min		3000			
Main	Spindle nose		ASA A2#11				
Spindle	Spindle bearing diameter (Front)	mm (inch)	160 (6.3)				
	Spindle through hole diameter	mm (inch)	115 (4.5)				
	Min. spindle indexing angle (C-axis	) deg	0.001				
	No. of tool stations	st	10 12				
	OD tool size	mm (inch)		25 (1.0)			
Turret	Boring bar diameter	mm (inch)	50 (2.0)				
	Indexing time (1st swivel time)	s	0.15				
	Rotary tool spindle speed	r/min	- 5000				
	Quill diameter	mm (inch)		100 / 100 / 120 / 120 (3.9 / 3.9 / 4.7 / 4.7)			
ail stock	Quill bore taper (Live)			MT#5			
	Quill travel	mm (inch)					
	Spindle speed (Belt [Built-in])	r/min		-			
	Spindle nose						
Sub-spindle	Spindle bearing diameter (Front)	mm (inch)		-			
	Spindle through hole diameter	mm (inch)					
	Min. spindle indexing angle (C-axis						
	Main spindle motor	kW (Hp)	22 / 18.5 (29.5 / 24.8)				
	Sub spindle motor	kW (Hp)	= 100 (a)				
Motors	Rotary tool spindle motor	kW (Hp)	5.5 [7.5] (7.4 [10.1])				
	Coolant pump motor	kW (Hp)	0.4 (0.5)				
ower source	Electric power supply (Rated capacit		41.64 / 41.64 / 42.83 / 42.83	44.42 / 44.42 / 45.61 / 45.61	46.40 / 46.40 / 47.59 / 47.59		
	Machine height	mm (inch)	2020/2020/2315/2315		2315 (91.1)		
	Machine dimension length	mm (inch)		4530/5615/5685 (153.9/178.3/221.1/2			
Machine size	width	mm (inch)		/2105/2280/2280(78.8/82.9/89.8/89			
		5850/ 7350/10150/11650	6500 / 8000 / 10800 / 12300				

]: Option

#### Standard feature

- Hydraulic power unit
- Lubrication equipment
- Coolant supply equipment
- Front guard door interlock
- · Hydraulic chuck & actuating cylinder
- Soft jaws
- Foot switch
- Standard tool kit (tool holder & boring sleeve)
- Work light
- Manuals
- Levelling jack screw & plates
- Hand tool kit (including small tool for operations)
- · Safety precaution name plates

### Optional feature

- · Additional tool holder & sleeves
- Air blast for chuck jaw cleaning
- Air gun
- · Automatic door with safety device
- Bar feeder interface
- Dual chucking pressure
- · Hardened & ground jaws
- Pressure switch for chucking pressure check
- High pressure coolant
- Oil skimmer
- Chip conveyor

- Chip bucket
- Programmable tail stock
- Servo driven tail stock
- Signal tower (yellow, red, green)
- Tail stock quill for dead center
- Tool pre-setter (Automatic type)
- Tool pre-setter (Manual type)
- Work ejector
- Parts catcher
- Parts conveyor
- Controller : Fanuc 31i

- The specifications and information above-mentioned may be changed without prior notice.
- For more details, please contact Doosan

# NC Unit Specifications

# Fanuc 31i

- Controlled path	1 path [2 path]
Controlled axes	X, Z, C, Y [C2, B]
Simultaneous controlled axes	4 axes
- Angular axis control	
- Axis control by PMC - Backlash compensation	0 ~ ±9999 pulses
Backlash compensation for each rapid	
- Chamfering on / off	
- Cs contouring control	
- HRV2 control	
- Least input command	0.001 / 0.0001 mm/inch
- Machine lock	All axis / each axis
- Mirror image	
- Overtravel - Position switch	
- Stored pitch error compensation	
Stored stroke check 1	
-Torque control	
Interference chek for rotary area	
Unexpected disturbance torque detect	ion function
OPERATION	
Automatic operation (memory)	
MDI operation	
- DNC Operation with Memory card - Buffer register	
- Burier register - Dry run	
- Handle incremental feed	X1, X10, X100
- Program restart	,-1100
Wrong operation prevention	
- JOG feed	
- Manual handle feed	1 unit
Manual intervention and return	
Manual pulse generator	1 ea
- Manual reference position return	
- Program number search - Refernce position setting without dog	
- Sequence number search	
INTERPOLATION FUNCTIONS	
INTERPOLATION FUNCTIONS - Nano interpolation - Positioning	
INTERPOLATION FUNCTIONS  - Nano interpolation  - Positioning  - 1st. Reference position return	Manual, G28
INTERPOLATION FUNCTIONS  - Nano interpolation  - Positioning  - 1st. Reference position return  - 2nd. reference position return	Manual, G28 G30
INTERPOLATION FUNCTIONS  Nano interpolation  Positioning  - 1st. Reference position return  2nd. reference position return  - 2nd. reference position return	Manual, G28 G30
- Single block INTERPOLATION FUNCTIONS - Nano interpolation - Positioning - 1st. Reference position return - 2nd. reference position return - Circular interpolation - Continuous threading - Cylindrical interpolation	Manual, G28 G30
INTERPOLATION FUNCTIONS  Nano interpolation  Positioning  1st. Reference position return  2nd. reference position return  Circular interpolation  Continuous threading  Cylindrical interpolation  Dwell (per sec)	Manual, G28 G30 G02
INTERPOLATION FUNCTIONS  Nano interpolation  Positioning  1st. Reference position return  2nd. reference position return  Circular interpolation  Continuous threading  Cylindrical interpolation  Dwell (per sec)  Linear interpolation	Manual, G28 G30 G02
INTERPOLATION FUNCTIONS  - Nano interpolation  - Positioning - 1st. Reference position return - 2nd. reference position return - Corcular interpolation - Continuous threading - Cylindrical interpolation - Dwell (per sec) - Linear interpolation - Multiple threading	Manual, G28 G30 G02
INTERPOLATION FUNCTIONS  - Nano interpolation  - Positioning - 1st. Reference position return - 2nd. reference position return - Circular interpolation - Continuous threading - Cylindrical interpolation - Dwell (per sec) - Linear interpolation - Multiple threading - Polar coordinate interpolation	Manual, G28 G30 G02
INTERPOLATION FUNCTIONS  Nano interpolation Positioning 1st. Reference position return 2nd. reference position return Circular interpolation Continuous threading Cylindrical interpolation Dwell (per sec) Linear interpolation Multiple threading Polar coordinate interpolation Helical interpolation	Manual, G28 G30 G02 G04 G01
INTERPOLATION FUNCTIONS  - Nano interpolation  - Positioning - Ist. Reference position return - 2nd. reference position return - Circular interpolation - Continuous threading - Cylindrical interpolation - Dwell (per sec) - Linear interpolation - Multiple threading - Polar coordinate interpolation - Helical interpolation - Reference position return check	Manual, G28 G30 G02 G04 G01
INTERPOLATION FUNCTIONS  - Nano interpolation  - Positioning  - 1st. Reference position return  - 2nd. reference position return  - Circular interpolation  - Continuous threading  - Cylindrical interpolation  - Dwell (per sec)  - Linear interpolation  - Multiple threading  - Polar coordinate interpolation  - Helical interpolation  - Reference position return check  - Skip	Manual, G28 G30 G02 G04 G01
INTERPOLATION FUNCTIONS  - Nano interpolation  - Positioning - 1st. Reference position return - 2nd. reference position return - Circular interpolation - Continuous threading - Cylindrical interpolation - Dwell (per sec) - Linear interpolation - Multiple threading - Polar coordinate interpolation - Helical interpolation - Reference position return check - Skip - Thread cutting / Synchronous cutting	Manual, G28 G30 G02 G04 G01
INTERPOLATION FUNCTIONS  Nano interpolation  Positioning  1st. Reference position return  2nd. reference position return  Circular interpolation  Continuous threading  Cylindrical interpolation  Dwell (per sec)  Linear interpolation  Multiple threading  Polar coordinate interpolation  Helical interpolation  Reference position return check  Skip  Thread cutting / Synchronous cutting  Thread cutting retract	Manual, G28 G30 G02 G04 G01
INTERPOLATION FUNCTIONS  Nano interpolation  Positioning  1st. Reference position return  2nd. reference position return  Corcular interpolation  Continuous threading  Cylindrical interpolation  Dwell (per sec)  Linear interpolation  Multiple threading  Polar coordinate interpolation  Helical interpolation  Reference position return check  Skip  Thread cutting / Synchronous cutting  Thread cutting retract  Torque limit skip	Manual, G28 G30 G02 G04 G01
INTERPOLATION FUNCTIONS  Nano interpolation  Positioning  1st. Reference position return  2nd. reference position return  Circular interpolation  Continuous threading  Cylindrical interpolation  Dwell (per sec)  Linear interpolation  Multiple threading  Polar coordinate interpolation  Helical interpolation  Reference position return check  Skip  Thread cutting / Synchronous cutting  Thread cutting retract  Torque limit skip	Manual, G28 G30 G02 G04 G01
INTERPOLATION FUNCTIONS  Nano interpolation  Positioning  1st. Reference position return  2nd. reference position return  Circular interpolation  Continuous threading  Cylindrical interpolation  Dwell (per sec)  Linear interpolation  Multiple threading  Polar coordinate interpolation  Helical interpolation  Reference position return check  Skip  Thread cutting / Synchronous cutting  Thread cutting retract  Torque limit skip  FEED FUNCTION  Automatic acceleration / deceleration	Manual, G28 G30 G02 G04 G01
INTERPOLATION FUNCTIONS  Nano interpolation  Positioning  1st. Reference position return  2nd. reference position return  Circular interpolation  Continuous threading  Cylindrical interpolation  Dwell (per sec)  Linear interpolation  Multiple threading  Polar coordinate interpolation  Helical interpolation  Reference position return check  Skip  Thread cutting / Synchronous cutting  Thread cutting retract  Torque limit skip  FEED FUNCTION  Automatic acceleration / deceleration  Cutting feedrate clamp	Manual, G28 G30 G02 G04 G01
INTERPOLATION FUNCTIONS  - Nano interpolation  - Positioning  - 1st. Reference position return  - 2nd. reference position return  - 2nd. reference position return  - Corrular interpolation  - Continuous threading  - Cylindrical interpolation  - Dwell (per sec)  - Linear interpolation  - Multiple threading  - Polar coordinate interpolation  - Helical interpolation  - Reference position return check  - Skip  - Thread cutting / Synchronous cutting  - Thread cutting retract  - Torque limit skip  - FEED FUNCTION  - Automatic acceleration / deceleration  - Cutting feedrate clamp  - Feed per minute	Manual, G28 G30 G02 G04 G01
INTERPOLATION FUNCTIONS  Nano interpolation Positioning - Ist. Reference position return - Ist. Reference position return - Interpolation - Continuous threading - Cylindrical interpolation - Continuous threading - Cylindrical interpolation - Dwell (per sec) - Linear interpolation - Multiple threading - Polar coordinate interpolation - Helical interpolation - Reference position return check - Skip - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per revolution	Manual, G28 G30 G02 G04 G01 G27 G31
INTERPOLATION FUNCTIONS  - Nano interpolation  - Positioning - Ist. Reference position return - 2nd. reference position return - Continuous threading - Cylindrical interpolation - Continuous threading - Cylindrical interpolation - Dwell (per sec) - Linear interpolation - Multiple threading - Polar coordinate interpolation - Helical interpolation - Reference position return check - Skip - Thread cutting / Synchronous cutting - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip  FEED FUNCTION - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per revolution - Feedrate override (10% unit)	Manual, G28 G30 G02 G04 G01 G27 G31
INTERPOLATION FUNCTIONS  - Nano interpolation  - Positioning - 1st. Reference position return - 2nd. reference position return - Corcular interpolation - Continuous threading - Cylindrical interpolation - Dwell (per sec)  - Linear interpolation - Multiple threading - Polar coordinate interpolation - Helical interpolation - Reference position return check - Skip - Thread cutting / Synchronous cutting - Thread cutting interpolation - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per minute - Feed per revolution - Feed override (10% unit) - Jog feed override (10% unit)	Manual, G28 G30 G02 G04 G01 G27 G31
INTERPOLATION FUNCTIONS  Nano interpolation  Positioning  1st. Reference position return  2nd. reference position return  Circular interpolation  Continuous threading  Cylindrical interpolation  Dwell (per see)  Linear interpolation  Multiple threading  Polar coordinate interpolation  Helical interpolation  Helical interpolation return check  Skip  Thread cutting / Synchronous cutting  Thread cutting retract  Torque limit skip  FEED FUNCTION  Automatic acceleration / deceleration  Feed per minute  Feed per revolution  Feedrate override (10% unit)  Manual per revolution feed	Manual, G28 G30 G02 G04 G01 G27 G31
INTERPOLATION FUNCTIONS  - Nano interpolation  - Positioning - Ist. Reference position return - 2nd. reference position return - Corcular interpolation - Continuous threading - Cylindrical interpolation - Dwell (per sec)  - Linear interpolation - Multiple threading - Polar coordinate interpolation - Multiple threading - Polar coordinate interpolation - Reference position return check - Skip - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip  FEED FUNCTION - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per minute - Feed per revolution - Feed ret override (10% unit) - Manual per revolution feed - Override cancel - Rapid traverse override	Manual, G28 G30 G02 G04 G01 G27 G31
INTERPOLATION FUNCTIONS  - Nano interpolation  - Positioning - Ist. Reference position return - 2nd. reference position return - Corcular interpolation - Continuous threading - Cylindrical interpolation - Dwell (per sec)  - Linear interpolation - Multiple threading - Polar coordinate interpolation - Multiple threading - Polar coordinate interpolation - Reference position return check - Skip - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip  FEED FUNCTION - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per minute - Feed per revolution - Feed ret override (10% unit) - Manual per revolution feed - Override cancel - Rapid traverse override	Manual, G28 G30 G02 G04 G01 G27 G31 G27 G31 0 - 200 % 0 - 2000 mm/min
INTERPOLATION FUNCTIONS  Nano interpolation  Positioning  1st. Reference position return  2nd. reference position return  Circular interpolation  Continuous threading  Cylindrical interpolation  Dwell (per sec)  Linear interpolation  Multiple threading  Polar coordinate interpolation  Helical interpolation  Reference position return check  Skip  Thread cutting / Synchronous cutting  Thread cutting retract  Torque limit skip  FEED FUNCTION  Automatic acceleration / deceleration  Cutting feedrate clamp  Feed per minute  Feed per revolution  Feedrate override (10% unit)  Manual per revolution feed  Override cancel  Rapid traverse override  Tangential speed constant control	Manual, G28 G30 G02 G04 G01 G27 G31 G27 G31 0 - 200 % 0 - 2000 mm/min
INTERPOLATION FUNCTIONS  - Nano interpolation  - Positioning - Ist. Reference position return - 2nd. reference position return - Circular interpolation - Continuous threading - Cylindrical interpolation - Continuous threading - Cylindrical interpolation - While the second interpolation - Multiple threading - Polar coordinate interpolation - Helical interpolation - Reference position return check - Skip - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip  FEED FUNCTION - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per minute - Feed per revolution - Feedrate override (10% unit) - Manual per revolution feed - Overide cancel - Rapid traverse override - Tangential speed constant control	Manual, G28 G30 G02 G04 G01 G27 G31 G27 G31 0 - 200 % 0 - 2000 mm/min
INTERPOLATION FUNCTIONS  - Nano interpolation  - Positioning - 1st. Reference position return - 2nd. reference position return - Contain underpolation - Continuous threading - Cylindrical interpolation - Dwell (per sec)  - Linear interpolation - Multiple threading - Polar coordinate interpolation - Multiple threading - Polar coordinate interpolation - Reference position return check - Skip - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip  - FEED FUNCTION - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per minute - Feed per revolution - Feed retract override (10% unit) - Jog feed override (10% unit) - Manual per revolution feed - Override cancel - Rapid traverse override - Tangential speed constant control - AUXILIARY / SPINDLE SPEED FUNCTION - Spindie orientation	Manual, G28 G30 G02 G04 G01 G27 G31 G27 G31 0 - 200 % 0 - 2000 mm/min
INTERPOLATION FUNCTIONS  Nano interpolation  Positioning  1st. Reference position return  2nd. reference position return  Circular interpolation  Continuous threading  Cylindrical interpolation  Dwell (per sec)  Linear interpolation  Multiple threading  Polar coordinate interpolation  Helical interpolation  Reference position return check  Skip  Thread cutting / Synchronous cutting  Thread cutting retract  Torque limit skip  FEED FUNCTION  Automatic acceleration / deceleration  Cutting feedrate clamp  Feed per minute  Feed per revolution  Feedrate override (10% unit)  Manual per revolution feed  Override cancel  Rapid traverse override  Tangential speed constant control  AUXILIARY / SPINDLE SPEED FUNCTION  Spindle orientation  Actual spindle speed output	Manual, G28 G30 G02 G04 G01 G27 G31 G27 G31 0 - 200 % 0 - 2000 mm/min
INTERPOLATION FUNCTIONS  Nano interpolation  Positioning  1st. Reference position return  2nd. reference position return  Circular interpolation  Continuous threading  Cylindrical interpolation  Dwell (per sec)  Linear interpolation  Multiple threading  Polar coordinate interpolation  Helical interpolation  Reference position return check  Skip  Thread cutting / Synchronous cutting  Thread cutting retract  Torque limit skip  FEED FUNCTION  Automatic acceleration / deceleration  Cutting feedrate clamp  Feed per minute  Feed per revolution  Feedrate override (10% unit)  Jog feed override (10% unit)  Manual per revolution feed  Override cancel  Rapid traverse override  Tangential speed constant control  AUXILIARY / SPINDLE SPEED FUNCTION  Spindle speed output  Auxiliary function lock	Manual, G28 G30 G02 G04 G01 G27 G31 G27 G31 0 - 200 % 0 - 2000 mm/min
INTERPOLATION FUNCTIONS  - Nano interpolation  - Positioning - Ist. Reference position return - 2nd. reference position return - Circular interpolation - Continuous threading - Cylindrical interpolation - Continuous threading - Cylindrical interpolation - Dwell (per sec) - Linear interpolation - Multiple threading - Polar coordinate interpolation - Helical interpolation - Reference position return check - Skip - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip  FEED FUNCTION - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per revolution - Feed red per revolution - Feedrate override (10% unit) - Manual per revolution feed - Override cancel - Rapid traverse override - Tangential speed constant control - AUXILIARY / SPINDLE SPEED FUNCTION - Spindie orientation - Actual spindle speed output - Auxillary function lock - Constant surface speed control	0-200 % 0-2000 mm/min F0,25,100 %
INTERPOLATION FUNCTIONS  Nano interpolation Positioning 1st. Reference position return 2nd. reference position return Circular interpolation Continuous threading Cylindrical interpolation Dwell (per see) Linear interpolation Multiple threading Polar coordinate interpolation Helical interpolation Helical interpolation Reference position return check Skip Thread cutting / Synchronous cutting Thread cutting retract Torque limit skip FEED FUNCTION Automatic acceleration / deceleration Cutting feedrate clamp Feed per minute Feed per revolution Feedrate override (10% unit) Manual per revolution Feedrate override (10% unit) Manual per revolution feed Override cancel Rapid traverse override Tangential speed constant control  AUXILIARY / SPINDLE SPEED FUNCTION Spindie orientation Actual spindle speed output Auxiliary function lock Constant surface speed control M-code function M3 digits	Manual, G28 G30 G02 G04 G01 G27 G31 G27 G31 0-200 % 0-2000 mm/min
INTERPOLATION FUNCTIONS  Nano interpolation  Positioning  1st. Reference position return  2nd. reference position return  Circular interpolation  Continuous threading  Cylindrical interpolation  Dwell (per sec)  Linear interpolation  Multiple threading  Polar coordinate interpolation  Helical interpolation  Reference position return check  Skip  Thread cutting / Synchronous cutting  Thread cutting retract  Torque limit skip  FEED FUNCTION  Auttomatic acceleration / deceleration  Cutting feedrate clamp  Feed per innute  Feed per revolution  Feed per revolution  Feed averride (10% unit)  Manual per revolution feed  Override cancel  Rapid traverse override  Tangential speed constant control  AUXILIARY / SPINDLE SPEED FUNCTION  AUXILIARY / SPINDLE SPEED FUNCTION  Auxiliary function lock  Constant surface speed control  M-code function M3 digits  Multi spindle control	Manual, G28 G30 G02 G04 G01 G27 G31  0-200 % 0-2000 mm/min F0, 25, 100 %
INTERPOLATION FUNCTIONS  Nano interpolation Positioning 1st. Reference position return 2nd. reference position return Circular interpolation Continuous threading Cylindrical interpolation Dwell (per see) Linear interpolation Multiple threading Polar coordinate interpolation Helical interpolation Helical interpolation Reference position return check Skip Thread cutting / Synchronous cutting Thread cutting retract Torque limit skip FEED FUNCTION Automatic acceleration / deceleration Cutting feedrate clamp Feed per minute Feed per revolution Feedrate override (10% unit) Manual per revolution Feedrate override (10% unit) Manual per revolution feed Override cancel Rapid traverse override Tangential speed constant control  AUXILIARY / SPINDLE SPEED FUNCTION Spindie orientation Actual spindle speed output Auxiliary function lock Constant surface speed control M-code function M3 digits	Manual, G28 G30 G02 G04 G01 G27 G31 0 - 200 % 0 - 2000 mm/min F0, 25, 100 %
INTERPOLATION FUNCTIONS  - Nano interpolation  - Positioning - Ist. Reference position return - 2nd. reference position return - Circular interpolation - Continuous threading - Cylindrical interpolation - Continuous threading - Cylindrical interpolation - While the sec - Linear interpolation - Multiple threading - Polar coordinate interpolation - Helical interpolation - Helical interpolation - Reference position return check - Skip - Thread cutting / Synchronous cutting - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip  FEED FUNCTION - Automatic acceleration / deceleration - Cutting feedrate clamp - Feed per minute - Feed per minute - Feed per revolution - Feed acceleration feed - Override cancel - Rapid traverse override - Tangential speed constant control - AUXILIARY / SPINDLE SPEED FUNCTION - Spindle orientation - Actual spindle speed output - Auxillary function lock - Constant surface speed control - Mi-code function M3 digits - Multi spindle control - Rigid tapping	Manual, G28 G30 G02 G04 G01 G27 G31  0-200 % 0-2000 mm/min F0, 25, 100 %
INTERPOLATION FUNCTIONS  - Nano interpolation  - Positioning - Ist. Reference position return - 2nd. reference position return - Circular interpolation - Continuous threading - Cylindrical interpolation - Continuous threading - Cylindrical interpolation - While the position return - Circular interpolation - Multiple threading - Polar coordinate interpolation - Helical interpolation - Reference position return check - Skip - Thread cutting / Synchronous cutting - Thread cutting / Synchronous cutting - Thread cutting retract - Torque limit skip  FEED FUNCTION - Automatic acceleration / deceleration - Cutting feed revolution - Feed per minute - Feed per minute - Feed per revolution - Feed rear override (10% unit) - Manual per revolution feed - Override cancel - Rapid traverse override - Tangential speed constant control - AUXILIARY / SPINDLE SPEED FUNCTION - Spindie orientation - Actual spindle speed output - Auxiliary function lock - Constant surface speed control - M- code function M3 digits - Multi spindle control - Rigid tapping - S-code function	Manual, G28 G30 G02 G04 G01 G27 G31  0 - 200 % 0 - 2000 mm/min F0, 25, 100 %  M3 digits S4/S5 digits

- Spindle Output switching	
PROGRAM INPUT	
- Absolute / incremental programming	
- Addition of custom macro common variab	
	100~#199, #500~#999
- Automatic coordinate system setting - Canned cycle for drilling / Turning	
- Canned cycle	
- Circular interpolation by R programming	
- Control in/out	
- Coordinate system setting	G50
- Coordinate system shift	
- Custom macro	1 1
<ul> <li>Decimal point programming / Pocket calcupoint programming</li> </ul>	mator type decimai
- Diameter/radius programming	(X axis)
- Direct drawing dimension programming	
-Direct input of coordinate system shift	
-G code system A	
-G code system B/C	
- Input unit 10 time multiply - Label skip	
- Macro executor	
- Manual absolute on and off	
- Maximum program dimension	±9 digi
- Multiple repetitive canned cycle	G70 - G70
-Multiple repetitive canned cycle II	
- Optional block skip	9 piece
- Parity check - Plane selection	G17, G18, G19
- Program file name	32 characters
- Program stop / end(M00, M01 / M02, M3	
- Programmable data input	G10
-Sequence number	N8 digi
- SUB program call	10 folds nested
- Tape code : ISO / EIA auto recognition	EIA auto recognition
TOOL FUNCTION / TOOL COMPENSATION	
- Automatic tool offset	
- Automatic tool offset - Direct input of offset value measured	
- Automatic tool offset - Direct input of offset value measured - Direct input of offset value measured B	T2+2 digit
- Automatic tool offset - Direct input of offset value measured - Direct input of offset value measured B - T-code function	T2+2 digit
- Automatic tool offset  - Direct input of offset value measured  - Direct input of offset value measured B  - T-code function  - Tool geometry / wear compensation  - Tool life management	T2+2 digit
- Automatic tool offset - Direct input of offset value measured - Direct input of offset value measured B - T-code function - Tool geometry / wear compensation - Tool life management - Tool Load Monitoring system *	T2+2 digit
-Automatic tool offset -Direct input of offset value measured -Direct input of offset value measured B -T-code function -Tool geometry / wear compensation -Tool life management -Tool Load Monitoring system * -Tool nose radius compensation	
-Automatic tool offset - Direct input of offset value measured - Direct input of offset value measured B - T-code function - Tool geometry / wear compensation - Tool life management - Tool Load Monitoring system * - Tool nose radius compensation - Tool offset	G43, G44, G49
- Automatic tool offset  - Direct input of offset value measured  - Direct input of offset value measured B  - T-code function  - Tool geometry / wear compensation  - Tool life management  - Tool Load Monitoring system *  - Tool nose radius compensation  - Tool offset  - Tool offset  - Tool offset	G43, G44, G4
TOOL FUNCTION / TOOL COMPENSATION  - Automatic tool offset  - Direct input of offset value measured  - Direct input of offset value measured B  - T-code function  - Tool geometry / wear compensation  - Tool life management  - Tool Tool and Monitoring system *  - Tool nose radius compensation  - Tool offset  - Tool offset  - Tool offset value counter input  - Y-axis offset	G43, G44, G49
-Automatic tool offset - Direct input of offset value measured - Direct input of offset value measured B - T-code function - Tool geometry / wear compensation - Tool lufe management - Tool Load Monitoring system * - Tool nose radius compensation - Tool offset - Tool offset pairs - Tool offset value counter input - Y-axis offset	G43, G44, G4
- Automatic tool offset - Direct input of offset value measured - Direct input of offset value measured B - T-code function - Tool geometry / wear compensation - Tool life management - Tool Load Monitoring system * - Tool nose radius compensation - Tool offset - Tool offset - Tool offset value counter input - Y-axis offset - Fool OPERATION	G43, G44, G4
-Automatic tool offset -Direct input of offset value measured -Direct input of offset value measured B -T-code function -Tool geometry / wear compensation -Tool life management -Tool Load Monitoring system * -Tool nose radius compensation -Tool offset -Tool offset -Tool offset -Tool offset value counter input -Y-axis offset -Tool offset value counter input -Y-axis offset	G43, G44, G4
-Automatic tool offset -Direct input of offset value measured -Direct input of offset value measured B -T-code function -Tool geometry / wear compensation -Tool life management -Tool Load Monitoring system * -Tool Load Monitoring system * -Tool offset rains -Tool offset pairs -Tool offset pairs -Tool offset value counter input -Y-axis offset -EDITING OPERATION - Back ground editting - Extended part program editing	G43, G44, G4
-Automatic tool offset -Direct input of offset value measured -Direct input of offset value measured B -T-code function -Tool geometry / wear compensation -Tool life management -Tool Load Monitoring system * -Tool nose radius compensation -Tool offset -Tool offset -Tool offset -Tool offset pairs -Tool offset value counter input -Y-axis offset -Y-axis offset -EDITING OPERATION -Back ground editting -Extended part program editing -Memory card edit & operation -Number of registered programs	G43, G44, G48 ±6 digits : 32 pairs
-Automatic tool offset -Direct input of offset value measured -Direct input of offset value measured B -Tecode function -Tool geometry / wear compensation -Tool life management -Tool Load Monitoring system * -Tool nose radius compensation -Tool offset -Tool offset -Tool offset -Tool offset value counter input -Y-axis offset value counter input -Y-axis offset -EDITING OPERATION -Back ground editing -Extended part program editing -Memory card edit & operation -Number of registered programs -Part program editing	G43, G44, G49 ±6 digits : 32 pairs
-Automatic tool offset -Direct input of offset value measured -Direct input of offset value measured B -T-code function -Tool geometry / wear compensation -Tool life management -Tool Load Monitoring system * -Tool Load Monitoring system * -Tool offset pairs -Tool offset pairs -Tool offset pairs -Tool offset value counter input -Y-axis offset -EDITING OPERATION -Back ground editting -Extended part program editing -Memory card edit & operation -Number of registered programs -Part program editing -Part program editing -Part program editing	G43, G44, G49 ±6 digits : 32 pairs
-Automatic tool offset -Direct input of offset value measured -Direct input of offset value measured B -T-code function -Tool geometry / wear compensation -Tool life management -Tool Load Monitoring system * -Tool Load Monitoring system * -Tool offset pairs -Tool offset pairs -Tool offset pairs -Tool offset value counter input -Y-axis offset -EDITING OPERATION -Back ground editting -Extended part program editing -Memory card edit & operation -Number of registered programs -Part program editing -Part program editing -Part program editing	G43, G44, G49 ±6 digits : 32 pairs
-Automatic tool offset -Direct input of offset value measured -Direct input of offset value measured B -T-code function -Tool geometry / wear compensation -Tool life management -Tool load Monitoring system * -Tool nose radius compensation -Tool offset -Tool offset -Tool offset -Tool offset -Tool offset -Tool offset pairs -Tool offset value counter input -Y-axis offset -Y-axis offset -EDITING OPERATION -Back ground editting -Extended part program editing -Memory card edit & operation -Number of registered programs -Part program editing -Part program storage size -Program protect	G43, G44, G49 ±6 digits : 32 pairs
-Automatic tool offset -Direct input of offset value measured -Direct input of offset value measured B -T-code function -Tool geometry / wear compensation -Tool life management -Tool Load Monitoring system * -Tool nose radius compensation -Tool offset -Tool offset -Tool offset -Tool offset -Tool offset -Tool offset value counter input -Y-axis offset -Pack ground editing -Extended part program editing -Memory card edit & operation -Number of registered programs -Part program editing -Part program storage size -Program protect	G43, G44, G49 ±6 digits : 32 pairs 500 ea 640 (256 Kbyte) m
-Automatic tool offset -Direct input of offset value measured -Direct input of offset value measured B -T-code function -Tool geometry / wear compensation -Tool life management -Tool load Monitoring system * -Tool nose radius compensation -Tool offset value counter input -Y-axis offset -Y-	G43, G44, G4 ±6 digits : 32 pairs 500 ee
-Automatic tool offset - Direct input of offset value measured - Direct input of offset value measured B - T-code function - Tool geometry / wear compensation - Tool geometry / wear compensation - Tool offset value measured B - T-code function - Tool offset measured B - Tool offset value counter input - Y-axis offset - Tool offset value counter input - Y-axis offset - EDITING OPERATION - Back ground editting - Extended part program editing - Memory card edit & operation - Number of registered programs - Part program editing - Part program storage size - Program protect - SETTING AND DISPLAY - Actual cutting feedrate display - Alarm history display	G43, G44, G49 ±6 digits : 32 pairs 500 ea 640 (256 Kbyte) m
-Automatic tool offset -Direct input of offset value measured -Direct input of offset value measured B -T-code function -Tool geometry / wear compensation -Tool Juff management -Tool Load Monitoring system * -Tool Tool and system sys	G43, G44, G49 ±6 digits : 32 pairs 500 ec 640 (256 Kbyte) m
-Automatic tool offset -Direct input of offset value measured -Direct input of offset value measured B -T-code function -Tool geometry / wear compensation -Tool life management -Tool Ioad Monitoring system * -Tool nose radius compensation -Tool offset -Tool offset -Tool offset -Tool offset -Tool offset pairs -Tool offset pairs -Tool offset value counter input -Y-axis offset -Tool offset pairs -Tool offset pai	G43, G44, G49 ±6 digits : 32 pairs 500 ee 640 (256 Kbyte) m
-Automatic tool offset -Direct input of offset value measured -Direct input of offset value measured B -T-code function -Tool geometry / wear compensation -Tool life management -Tool load Monitoring system * -Tool nose radius compensation -Tool offset value counter input -Y-axis offset -Y-x	G43, G44, G49 ±6 digits : 32 pairs 500 ea 640 (256 Kbyte) m
-Automatic tool offset -Direct input of offset value measured -Direct input of offset value measured B -T-code function -Tool geometry / wear compensation -Tool geometry / wear compensation -Tool offset -Tool tood Monitoring system * -Tool nose radius compensation -Tool offset -Tool offset -Tool offset -Tool offset -Tool offset -Tool offset value counter input -Y-axis offset -Tool offset -	G43, G44, G49 ±6 digits : 32 pairs 500 ea 640 (256 Kbyte) m
-Automatic tool offset -Direct input of offset value measured -Direct input of offset value measured B -T-code function -Tool geometry / wear compensation -Tool life management -Tool load Monitoring system * -Tool nose radius compensation -Tool offset -Tool offset -Tool offset -Tool offset -Tool offset -Tool offset pairs -Tool offset pairs -Tool offset value counter input -Y-axis offset -Tool offset pairs -To	G43, G44, G49 ±6 digits : 32 pairs 500 ec 640 (256 Kbyte) m
-Automatic tool offset -Direct input of offset value measured -Direct input of offset value measured B -T-code function -Tool geometry / wear compensation -Tool life management -Tool load Monitoring system * -Tool nose radius compensation -Tool offset value counter input -Y-axis offset -Tool off	G43, G44, G49 ±6 digits : 32 pairs  500 ee 640 (256 Kbyte) m
-Automatic tool offset - Direct input of offset value measured - Direct input of offset value measured B - T-code function - Tool geometry / wear compensation - Tool geometry / wear compensation - Tool offset value measured B - T-code function - Tool offset value compensation - Tool offset pairs - Tool offset value counter input - Y-axis offset - EDITING OPERATION - Back ground editting - Extended part program editing - Memory card edit & operation - Number of registered programs - Part program editing - Part program storage size - Program protect - SETTING AND DISPLAY - Actual cutting feedrate display - Alarm history display - Current position display - Periodic maintenance screen - Display of spindle speed and T code at all - Help function - Multi-language display - Operation history display - Parameter setting and display - Parameter setting and display - Parameter setting and display	G43, G44, G49 ±6 digits : 32 pairs  500 ea 640 (256 Kbyte) m
-Automatic tool offset - Direct input of offset value measured - Direct input of offset value measured B - T-code function - Tool geometry / wear compensation - Tool geometry / wear compensation - Tool offset value measured B - T-code function - Tool offset measured B - Tool offset value compensation - Tool offset value counter input - Y-axis offset - Tool offset value counter input - Y-axis offset - Tool offset value counter input - Y-axis offset - Tool offset value counter input - Y-axis offset - Tool offset value counter input - Y-axis offset - Tool offset value counter input - Y-axis offset - Tool offset value counter input - Y-axis offset - Tool offset value counter input - Y-axis offset - Tool offset value counter input - Y-axis offset - Tool offset value counter input - Y-axis offset - Tool offset value counter input - Number of registered program editing - Part program editing - Part program storage size - Program protect - Program protect - SETTING AND DISPLAY - Actual cutting feedrate display - Alarm history display - Current position display - Periodic maintenance screen - Display of spindle speed and T code at all - Help function - Multi-language display - Operation history display - Parameter setting and display - Program comment display	G43, G44, G49 ±6 digits : 32 pairs  500 ea 640 (256 Kbyte) m
-Automatic tool offset - Direct input of offset value measured - Direct input of offset value measured B - T-code function - Tool geometry / wear compensation - Tool life management - Tool life management - Tool offset - Tool nose radius compensation - Tool offset value counter input - Y-axis offset - Tool offset value counter input - Y-axis offset - Tool offset - Tool offset value counter input - Y-axis offset - Tool offset value counter input - Y-axis offset - Tool offset	G43, G44, G49 ±6 digits : 32 pairs  500 ee 640 (256 Kbyte) m
-Automatic tool offset - Direct input of offset value measured - Direct input of offset value measured B - T-code function - Tool geometry / wear compensation - Tool geometry / wear compensation - Tool offset value measured B - T-code function - Tool offset value compensation - Tool offset - Too	G43, G44, G49 ±6 digits : 32 pairs  500 ea 640 (256 Kbyte) m
-Automatic tool offset -Direct input of offset value measured -Direct input of offset value measured B -T-code function -Tool geometry / wear compensation -Tool life management -Tool load Monitoring system * -Tool nose radius compensation -Tool offset -Tool offset -Tool offset -Tool offset -Tool offset -Tool offset pairs -Tool offset pairs -Tool offset value counter input -Y-axis offset -Tool offset pairs -Tool offset or value counter input -Y-axis offset -Tool offset or value counter input -Y-axis offset -Tool offset value counter input -Y-axis offset -Tool offset or value counter input -Y-axis offset -Tool offset or value counter input -Y-axis offset -Tool offset pairs -Tool	screens 31 characters
-Automatic tool offset - Direct input of offset value measured - Direct input of offset value measured B - T-code function - Tool geometry / wear compensation - Tool geometry / wear compensation - Tool offset value measured B - T-code function - Tool offset value compensation - Tool offset - Too	G43, G44, G45 ±6 digits : 32 pairs  500 ee 640 (256 Kbyte) m

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[]: PUMA 2100/2600 SY/LSY only

\*: According to the business contract made Doosan, some regions have "Tool Load Monitoring system" as option.

# NC Unit Specifications

## DOOSAN-Fanuc i series

	of series
AXES CONTROL	
- Controlled path	1 path [2 path]
- Controlled axes	X, Z, C, Y [C2, B]
- Simultaneous controlled axes	4 axes
- Axis control by PMC	
- Backlash compensation	0 ~ ±9999 pulses
- Backlash compensation for each rapid traverse and cutting feed	
- Chamfering on / off	
- Cs contouring control	
- HRV2 control	
- Least input command	0.001/0.0001 mm/inch
- Machine lock	All axis / each axis
- Mirror image	
- Overtravel	
- Stored pitch error compensation	
- Stored stroke check 1	
- Chuck and tail stock barrier	
- Stored stroke 2 and 3	
- Stroke limit check before move	
- Torque control	
OPERATION	
- Automatic operation (memory)	
- MDI operation	
- DNC Operation with Memory card	
- Dry run	
- Handle incremental feed	X1, X10, X100
- Program restart	
- Wrong operation prevention	
- JOG feed	
- Manual handle feed	Lunit

- Automatic operation (memory)	
- MDI operation	
- DNC Operation with Memory card	
- Dry run	
- Handle incremental feed	X1, X10, X100
- Program restart	
- Wrong operation prevention	
- JOG feed	
- Manual handle feed	1unit
- Manual intervention and return	
- Manual reference position return	
- Program number search	
- Refernce position setting without dog	
- Sequence number search	
- Single block	
- DNC operation (Reader / puncher interface is	required)
- Manual handle interruption	
- Reference position shift	

INTERPOLATION I	FUNCTIONS
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INTERFOLATION FUNCTIONS	
- Nano interpolation	
- Positioning	G00
- 1st. Reference position return	Manual, G28
- 2nd. reference position return	G30
- Circular interpolation	G02
- Continuous threading	
- Cylindrical interpolation	
- Dwell (per sec)	G04
- Helical interpolation	
- Linear interpolation	G01
- Multiple threading	
- Polar coordinate interpolation	
- Reference position return check	G27
- Skip	G31
- Thread cutting / Synchronous cutting	
- Thread cutting retract	
- Torque limit skip	
- 3rd / 4th reference point reurn	
- Polygon machining with two spindle	
- Variable lead threading	

#### FEED FUNCTION

- Automatic acceleration / deceleration	
- Cutting feedrate clamp	
- Feedrate override (10% unit)	0 - 200 %
- Jog feed override (10% unit)	0 - 2000 mm/min
- Override cancel	
- Rapid traverse override	F0, 25, 100 %
AUXILIARY / SPINDLE SPEED FUNCTION	
AUXILIARY / SPINDLE SPEED FUNCTION - Spindle orientation	
- Spindle orientation	
- Spindle orientation - Actual spindle speed output	
- Spindle orientation - Actual spindle speed output - Auxiliary function lock	M3 digits
- Spindle orientation - Actual spindle speed output - Auxiliary function lock - Constant surface speed control	M3 digits

#### PROGRAM INPUT

- Rigid tapping

- S-code function - Spindle serial output

- Spindle speed override

- G code system A / B / C - Label skip

- [Spindle sychronous control]

- Absolute / incremental programming
- Addition of custom macro common variables
#100~#199,#500~#999
- Automatic coordinate system setting

- Automatic coordinate system setting	
- Canned cycle for drilling / Turning	
- Circular interpolation by R programming	
- Coordinate system setting	G50
- Custom macro	
- Pocket calculator type decimal point programming	
- Diameter/radius programming (X axis)	
- Direct drawing dimension programming	
- Direct input of coordinate system shift	

- Macro executor	
- Manual absolute on and off	
- Maximum program dimension	±9 digit
- Multiple repetitive canned cycle	G70 - G76

- Multiple repetitive carried cycle if	
- Optional block skip	9 piece
- Parity check	
- Plane selection	G17, G18, G19
- Program file name	32 characters
- Program stop / end (M00, M01 / M02, M	30)

- Plane selection	G17, G18, G19
- Program file name	32 characters
- Program stop / end (M00, M01 / M02, N	130)
- Programmable data input	G10
- Sequence number	N8 digit
- SUB program call	10 folds nested
- Work coordinate system	G52-G59
- Interruption type custom macro	
- Optional block skip	9 piece
- Pattern data input	

### TOOL FUNCTION / TOOL COMPENSATION

TOOL FUNCTION / TOOL COMPENSATION	
- Automatic tool offset	
- T-code function	T2+2 digits
-Tool geometry / wear compensation	
- Tool life management	
-Tool Load Monitoring system *	
- Tool nose radius compensation	
-Tool offset	G43, G44, G49
- Tool offset pairs	+6 digits : 64 pairs

Tool offset value counter input	
Y-axis offset	

EDITING OPERATION	
- Number of registered programs	400 ea
- Part program editing	
- Part program storage size	1280m (512kB)
- Play back	

#### SETTING AND DISPLAY

- Alarm history display	
- Multi-language display	
- Program comment display	31 characters
- Run hours / part count display	
- Self-diagnosis function	
- Operating monitor screen	

#### DATA INPUT / OUTPUT

- External work number search	15 points
- Memory card input/output	
- RS232C interface	
- Automatic data backup	
- Screen hard copy	

#### OTHERS

S4 / S5 digits

S4/S5 digits

0 - 150 %

OTHERS	
- Cycle start and lamp	
- Display unit	10.4" Color LCD
- Feed hold and lamp	
- MDI unit	
- NC and servo ready	
- PMC system	

#### INTERFACE FUNCTION

- Ethernet function	Embedded etherne

#### OPERATION GUIDANCE FUNCTION

- EZ Guidei (Conversational Programming Solution)

#### OPTIONAL SPECIFICATIONS

### INTERPOLATION FUNCTIONS

- Multi step skip

#### FEED FUNCTION

- Advanced preview control

#### TOOL FUNCTION / TOOL COMPENSATION

-Tool offset pairs 99 / 200 pairs

#### DATA INPUT / OUTPUT

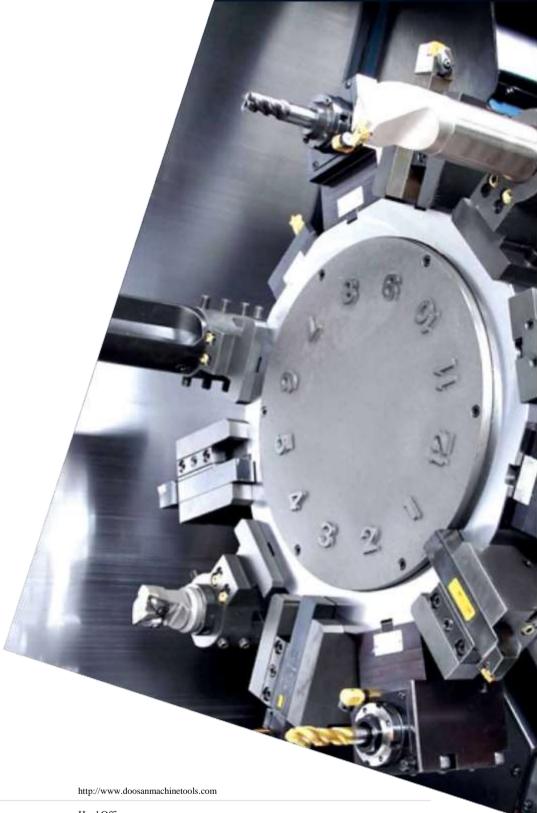
- Fast ethernet / Data server Only for 1 path

#### ROBOT INTERFACE

- Robot interface with PMC I/O module (Hardware between PMC I/O mudules) - Robot interface with PROFIBUS-DP

#### []: PUMA 2100/2600 SY/LSY only

\*: According to the business contract made Doosan, some regions have "Tool Load Monitoring system" as option.



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<sup>-</sup> The specifications and information above-mentioned may be changed without prior notice. - For more details, please contact Doosan.